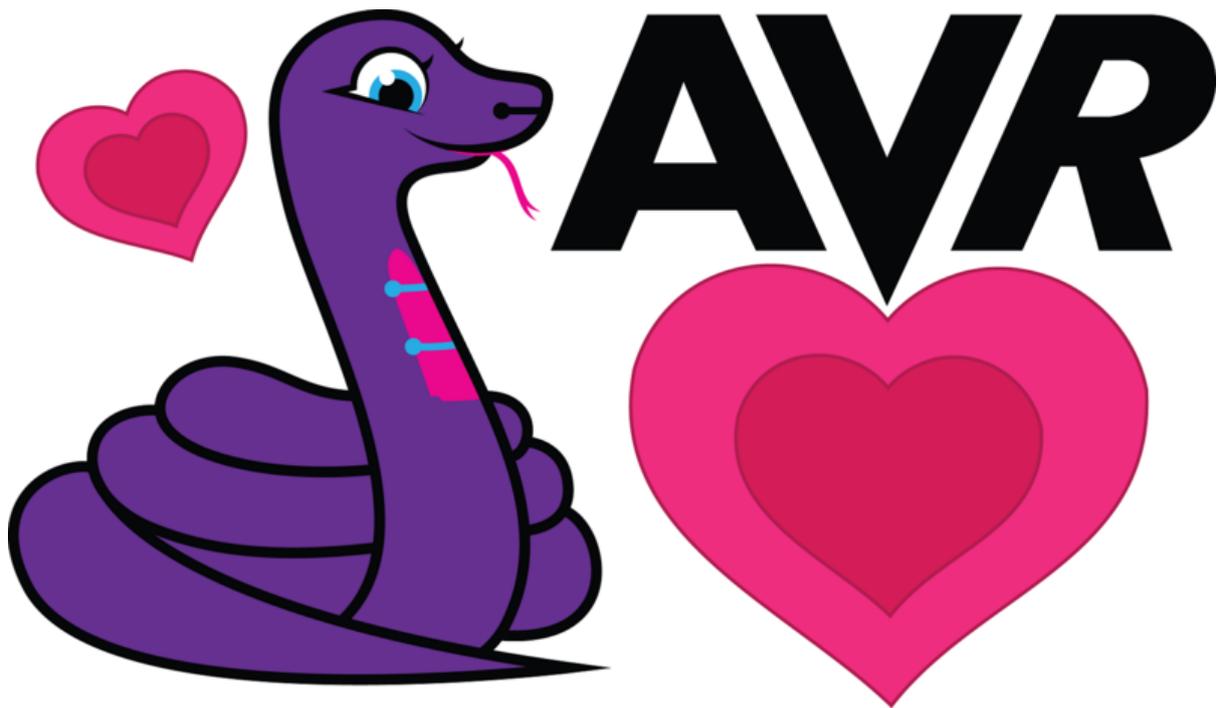




Stand-alone programming AVRs using CircuitPython

Created by lady ada



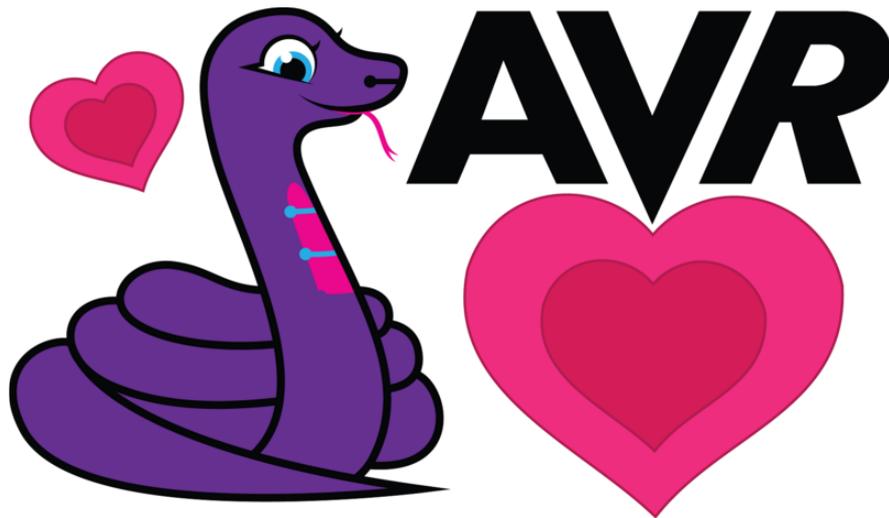
<https://learn.adafruit.com/stand-alone-programming-avrs-using-circuitpython>

Last updated on 2024-06-03 02:16:50 PM EDT

Table of Contents

Overview	3
<ul style="list-style-type: none">• Supported Chips	
Wiring	4
<ul style="list-style-type: none">• Power Pins• Data Pins• Wiring Diagram for Raw ATmega328 Chip• Wiring for Arduino Compatible	
Software Setup	6
<ul style="list-style-type: none">• Installing Library• Imports• Initialize hardware• Communication / Signature Check• Full Example• SPI / Wiring Errors	
Programming Chips	10
AVRprog API	12
<ul style="list-style-type: none">• Defining Chips• Verify Signature• Erasing Chip• Fuses• Flash• EEPROM	

Overview



If you've ever wanted a stand alone AVR programmer, that is super easy to use, you've come to the right place!

This guide will show you how to turn any CircuitPython powered board with 4+ GPIO pins into an AVR progammer all on its own. **No software like avrdude is needed**, this software will program the chip all on its own, just drag the HEX file onto the CircuitPython disk drive.

Perfect to putting bootloaders on empty chips, or field-reprogramming a project!

Supported Chips

In theory, any and all AVR chips with SPI-programming interfaces are supported. However, we only have examples for **ATmega328P** chips (used in Arduino compatibles), **ATtiny85** (used in original Trinket/Gemma), and **ATmega2560** (Arduino Mega compatibles)

To program other chips, you'll need to find out the signature, size of the flash, and the flash-page size. You can find this in the datasheet or in [avrdude.conf](#)

This code only supports SPI-based programming, not JTAG, SWD or parallel!

Wiring

Nearly all AVR's have a 'serial' programming interface, that's what we'll be using to program them. If your chip requires SWD, JTAG or parallel, this software won't work!

In this example we'll show how to wire up an existing Arduino 328P compatible or raw 328P chip to a Feather M0 for programming

For other chips, the wiring is similar, but you'll need to look up which pins are Power, Ground, Reset, and SCK/MOSI/MISO

Power Pins

Do these pins first because they're easy to forget!

- If connecting to a Arduino-compatible: connect **GND** on the Arduino to **GND** on the Feather. Then either plug the Arduino into USB, or connect the Arduino **5V** to Feather **USB**
- If connecting to a bare chip: connect both **GND** pins together and to the Feather **GND**. Connect **AVCC** to **VCC** to the Feather **3V** pin

If you're breadboarding a bare ATmega328 chip, don't forget there are **two** power pins and **two** ground pins

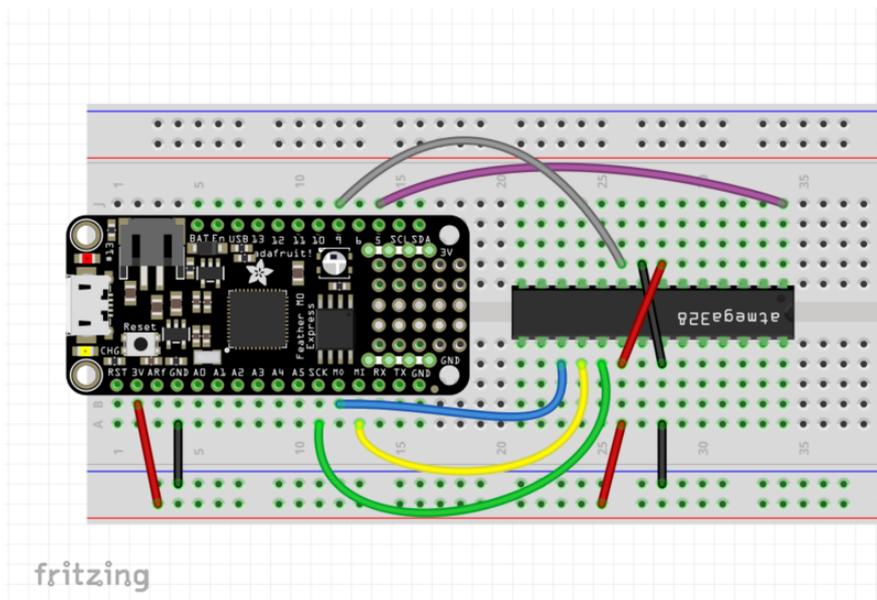
Data Pins

- Connect the **CircuitPython SCK** pin to the target **SCK** (on Uno/Atmega328 this is also known as Digital #13)
- Connect the **CircuitPython MISO** pin to the target **MISO** (on Uno/Atmega328 this is also known as Digital #12)
- Connect the **CircuitPython MOSI** pin to the target **MOSI** (on Uno/Atmega328 this is also known as Digital #11)
- Connect **CircuitPython D5** (or any digital pin, as long as you change the code too) to the target **RESET**

If you are breadboarding a chip, it may need a clock or crystal and it needs to be there to program the chip! If your board has a crystal or oscillator already, skip this. If you're programming a 'raw' ATmega328, you'll want to add it:

- Connect CircuitPython D9 (or any digital pin with PWM out, as long as you change the code to) to the target **XTAL1**

Wiring Diagram for Raw ATmega328 Chip



Fritzing for diagram

<https://adafru.it/AsI>

Pin-out

Figure 5-1. 28-pin PDIP

(PCINT14/RESET) PC6	1	28	PC5 (ADC5/SCL/PCINT13)
(PCINT16/RXD) PD0	2	27	PC4 (ADC4/SDA/PCINT12)
(PCINT17/TXD) PD1	3	26	PC3 (ADC3/PCINT11)
(PCINT18/INT0) PD2	4	25	PC2 (ADC2/PCINT10)
(PCINT19/OC2B/INT1) PD3	5	24	PC1 (ADC1/PCINT9)
(PCINT20/XCK/T0) PD4	6	23	PC0 (ADC0/PCINT8)
VCC	7	22	GND
GND	8	21	AREF
(PCINT6/XTAL1/TOSC1) PB6	9	20	AVCC
(PCINT7/XTAL2/TOSC2) PB7	10	19	PB5 (SCK/PCINT5)
(PCINT21/OC0B/T1) PD5	11	18	PB4 (MISO/PCINT4)
(PCINT22/OC0A/AIN0) PD6	12	17	PB3 (MOSI/OC2A/PCINT3)
(PCINT23/AIN1) PD7	13	16	PB2 (SS/OC1B/PCINT2)
(PCINT0/CLKO/ICP1) PB0	14	15	PB1 (OC1A/PCINT1)

VCC lines are Red

Ground/GND lines are Black

SCK is green

MOSI is blue

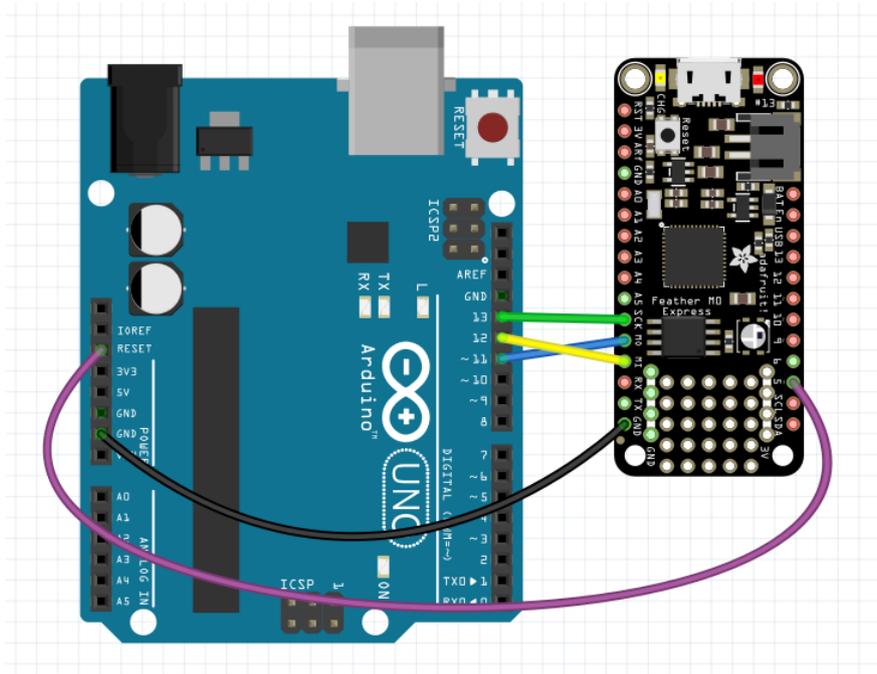
MISO is yellow

RESET is purple

XTAL is grey

Notice that the notch on the chip is to the right - away from the Feather!

Wiring for Arduino Compatible



Fritzing for diagram

<https://adafru.it/AsJ>

For Arduino UNO and compatibles, we recommend powering from USB or DC power. Then connect **GND** pins together, and wire up **Reset**, **SCK**, **MOSI**, and **MISO** as seen above.

XTAL pin is not required, Arduinos have on-board crystals.

Software Setup

Installing Library

To use the AVR programming library you'll need to install the [Adafruit CircuitPython AVRprog](https://adafru.it/CiO) (<https://adafru.it/CiO>) library on your CircuitPython board.

First make sure you are running the [latest version of Adafruit CircuitPython](https://adafru.it/Amd) (<https://adafru.it/Amd>) for your board.

Next you'll need to install the necessary libraries to use the hardware--carefully follow the steps to find and install these libraries from [Adafruit's CircuitPython library](#)

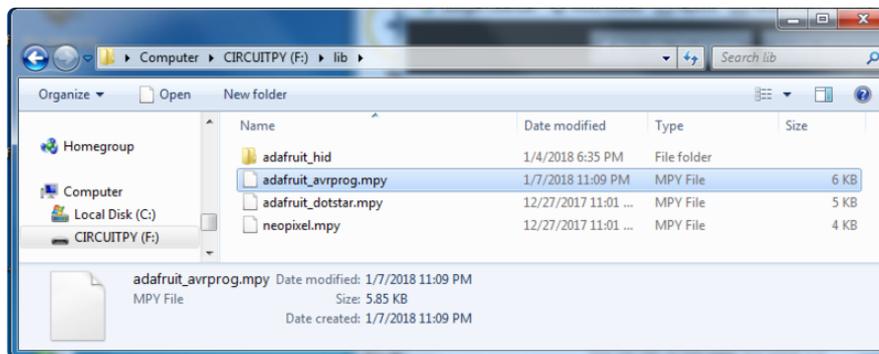
[bundle \(https://adafru.it/zdx\)](https://adafru.it/zdx). Our introduction guide has [a great page on how to install the library bundle \(https://adafru.it/ABU\)](https://adafru.it/ABU) for both express and non-express boards.

Remember for non-express boards like the Trinket M0, you'll need to manually install the necessary library from the bundle:

- `adafruit_avrprog.mpy`

You can also download the `adafruit_avrprog.mpy` from [its releases page on Github \(https://adafru.it/CiP\)](https://adafru.it/CiP).

Before continuing make sure your board's lib folder or root filesystem has the `adafruit_avrprog.mpy` file copied over.



Next [connect to the board's serial REPL \(https://adafru.it/Awz\)](https://adafru.it/Awz) so you are at the CircuitPython >>> prompt.

For this simple example, we're assuming you don't need a clock-driving pin here, if you do, see the full example at the end of the page!

Imports

You'll need to import a few libraries

- `board` - for assigning hardware pins
- `busio` - we use SPI bus to talk to the target device
- `adafruit_avrprog` - the library that we're using!

```
>>> import board
>>> import busio
>>> import adafruit_avrprog
```

```
Press any key to enter the REPL. Use CTRL-D to reload.
Adafruit CircuitPython 2.2.0 on 2018-01-02; Adafruit Trinket M0 with samd21e18
>>> import board
>>> import busio
>>> import adafruit_avrprog
>>>
```

Initialize hardware

Next, create the hardware interface, you'll need an SPI port and one extra pin for the reset line. We'll use `board.D5` to match our diagrams on the previous page, but it can be any pin you like!

```
>>> spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
>>> avrprog = adafruit_avrprog.AVRprog()
>>> avrprog.init(spi, board.D5)
```

Communication / Signature Check

Next we'll verify that we can talk to the chip, once that works we are best off crafting our programmer into a full `main.py` project but at least we can quickly determine if things worked out.

1. Start by initializing the programming interface with `avrprog.begin()` which will pull the `reset` line low and send some commands to get the chip to listen.
2. Then read the signature, you'll get an array of numbers - its probably best to turn this into hex values before printing since they're referred to as hex values in datasheets.
3. Finally, call `avrprog.end()`

```
>>> avrprog.begin()
>>> [hex(i) for i in avrprog.read_signature()]
['0x1e', '0x95', '0xf']
>>> avrprog.end()
```

```
>>> avrprog.begin()
>>> [hex(i) for i in avrprog.read_signature()]
['0x1e', '0x95', '0xf']
>>> avrprog.end()
```

You can see here we have a 0x1E950F chip attached, also known as an **ATmega328P**

Full Example

You can save this code to `main.py` and use the REPL to see the signature data, it also includes the code for setting up the crystal-driving PWM output

```
# SPDX-FileCopyrightText: 2021 ladyada for Adafruit Industries
# SPDX-License-Identifier: MIT

"""
Read Signature Test - All this does is read the signature from the chip to
check connectivity!
"""

import board
import busio
import pwmio
import adafruit_avrprog

spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
avrprog = adafruit_avrprog.AVRprog()
avrprog.init(spi, board.D5)

# pylint: disable-msg=no-member
# we can generate an 6 MHz clock for driving bare chips too!
clock_pwm = pwmio.PWMOut(board.D9, frequency=6000000, duty_cycle=65536 // 2)
# pylint: enable-msg=no-member

avrprog.begin()
print("Signature bytes: ", [hex(i) for i in avrprog.read_signature()])
avrprog.end()
```

SPI / Wiring Errors

If something went wrong, you'll get an `SPI transaction failed` exception. Check your wiring! Also, sometimes the chip doesn't quite hear us, try connecting again.

Common problems:

- The target isn't powered - make sure it is powered via USB or via the CircuitPython board. A shared Ground wire is required
- Make sure you have the reset pin on the target connected to whatever pin you setup when you created the `avrprog` object
- On ATmega2560, MOSI and MISO are connected opposite than the way you think. Either way, its OK to try swapping those two wires, see if that helps!
- The target is expecting a crystal but you don't have one, for example the UNO bootloader requires that the chip have a crystal or oscillator connected up, it's not optional!

Programming Chips

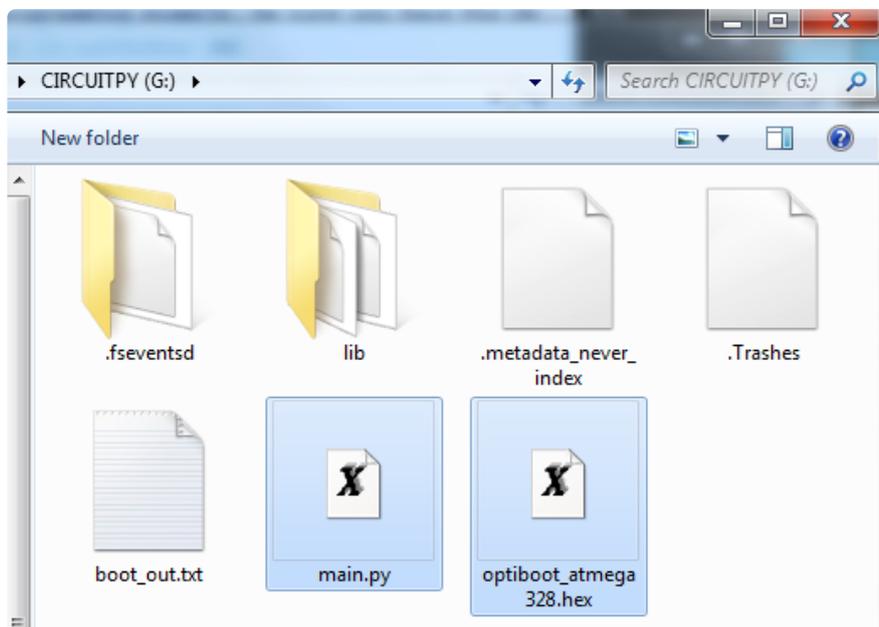
OK now that you've read the signature, you can write some code!

We have a few examples available you can use 'out of the box' - all are available [here \(https://adafru.it/CiR\)](https://adafru.it/CiR). You can [download the library zip to get all the files \(https://adafru.it/CiT\)](https://adafru.it/CiT). For each programming demo, we also have a matching 'hex' file, that's a requirement - it's the file you'll be programming into the chip!

Copy the programming sketch into **main.py** and also grab the matching hex file. For example:

```
"""  
UNO Optiboot programming example, be sure you have the UNO wired up so:  
  UNO Ground to CircuitPython GND  
  UNO 5V to CircuitPython USB or make sure the UNO is powered by USB  
  UNO Pin 13 -&gt; CircuitPython SCK  
  UNO Pin 12 -&gt; CircuitPython MISO  
  UNO Pin 11 -&gt; CircuitPython MOSI  
  UNO RESET -&gt; CircuitPython D5 (or change the init() below to change it!)  
Drag "optiboot_atmega328.hex" onto the CircuitPython disk drive, then open REPL!  
"""
```

Indicates you need **optiboot_atmega328.hex**



Then run the REPL and look for the **Ready to GO, type 'G' here to start >** prompt and type the letter G into the REPL. You should see the code begin by checking the identity of the chip (the signature), erasing the chip, then programming it.

```

main.py output:
Ready to GO, type 'G' here to start> G
Found signature: ['0x1e', '0x95', '0xf']
Found ATmega328P
Programming flash from file
Erasing chip....
Programming page $0000...skipping
Programming page $0080...skipping
Programming page $0100...skipping
Programming page $0180...skipping
Programming page $0200...skipping

```

It will skip most of the flash 'pages' because they're empty. At the end you'll get to the pages that are flashed and verified:

```

Programming page $7C00...skipping
Programming page $7C80...skipping
Programming page $7D00...skipping
Programming page $7D80...skipping
Programming page $7E00...Verifying page @ $7E00
Programming page $7E80...Verifying page @ $7E80
Programming page $7F00...Verifying page @ $7F00
Programming page $7F80...Verifying page @ $7F80
Done!

```

It's very very rare for something to go wrong during verification. But if it does you'll see something like this. Just start over by hitting ^C and ^D in the REPL to begin again.

```

Programming page $7D80...skipping
Programming page $7E00...Verifying page @ $7E00
Programming page $7E80...Verifying page @ $7E80
Programming page $7F00...Verifying page @ $7F00
Verify fail at address 7F00
Page should be: bytearray(b"\xa6\x01\xa0\xe0\xb1\xe0,\x910\xe0\x11\x96\x8c
\x91\x11\x97\x90\xe0\x98/\x88'\x82+\x93+\x12\x96\xfa\x01\x0c\x01\x87\xbe\xe8\x95\x11$N_0
\xf1\xe0\xa08\xbf\x07Q\xf7\xf6\x01\xa7\xbe\xe8\x95\x07\xb6\x00\xfc\xfd\xcf\x97\xbe\xe8\x95&
\xc0\x847\xb1\xf4.\xd0-\xd0\xf8.+ \xd0<\xd0\xf6\x01\xef,\xf8f\x01\x0f_\x1f0\x84\x91\x1b\xd0\xea
\x94\xf8\x01\xc1\xf7\x08\x94\xc1\x1c\xd1\x1c\xfa\x94\xcf\x0c\xd1\x1c\x0e
\xc0\x8579\xf4(\xd0\x8e\xe1\x0c\xd0\x85\xe9")
But contains: bytearray(b"\xa6\xff\xa0\xe0\xb1\xe0,\x910\xe0\x11\x96\x8c
\x91\x11\x97\x90\xe0\x98/\x88'\x82+\x93+\x12\x96\xfa\x01\x0c\x01\x87\xbe\xe8\x95\x11$N_0
\xf1\xe0\xa08\xbf\x07Q\xf7\xf6\x01\xa7\xbe\xe8\x95\x07\xb6\x00\xfc\xfd\xcf\x97\xbe\xe8\x95&
\xc0\x847\xb1\xf4.\xd0-\xd0\xf8.+ \xd0<\xd0\xf6\x01\xef,\xf8f\x01\x0f_\x1f0\x84\x91\x1b\xd0\xea
\x94\xf8\x01\xc1\xf7\x08\x94\xc1\x1c\xd1\x1c\xfa\x94\xcf\x0c\xd1\x1c\x0e
\xc0\x8579\xf4(\xd0\x8e\xe1\x0c\xd0\x85\xe9")
Done!

```

That's it! You've programmed the chip. For more details, keep reading.

AVRprog API

Defining Chips

Before you can really do anything you need to tell AVRprog library what the chip is. We'll use a python dict for that. Define **name** (that's for your information and printing errors), **sig** - a list of the three-byte signature, **flash_size** - the size of the flash memory in bytes, **page_size** - the size of each flash memory page in bytes, and **fuse_mask** - a list of the four fuses in a list `[low, high, ext, lock]`

Fuse mask is the oddest one, but basically it defines which bits are actually used in each fuse. For example, the ext fuse is often only the bottom three bits, so its **0x07**. If you're not sure, you can set all four to **0xFF** and then when you burn fuses, set all the high bits to 1.

Here are some chip examples:

```
attiny85 = {'name': "ATtiny85"}
attiny85['sig'] = [0x1E, 0x93, 0x0B]
attiny85['flash_size'] = 8192
attiny85['page_size'] = 64
attiny85['fuse_mask'] = (0xFF, 0xFF, 0x07, 0x3F)
```

```
atmega328p = {'name': "ATmega328P"}
atmega328p['sig'] = [0x1E, 0x95, 0x0F]
atmega328p['flash_size'] = 32768
atmega328p['page_size'] = 128
atmega328p['fuse_mask'] = (0xFF, 0xFF, 0x07, 0x3F)
```

```
atmega2560 = {'name': "ATmega2560"}
atmega2560['sig'] = [0x1E, 0x98, 0x01]
atmega2560['flash_size'] = 262144
atmega2560['page_size'] = 256
atmega2560['fuse_mask'] = (0xFF, 0xFF, 0x07, 0x3F)
```

Verify Signature

```
avrprog.verify_sig(chip_dict, verbose=True)
```

We suggest calling this first, you can call it whenever you like, and it will return True/False. `chip_dict` is that dictionary you made above

Erasing Chip

This one is easy, just call `avrprog.erase_chip()` - the chip erase command is the same for all chips. It may take a second on bigger chips. **You must do this before programming new firmware!**

Also, if your chip has the lock-firmware-fuse set, you may have to erase the flash before you can change the lock fuse.

Fuses

You can read, write and verify fuses.

Read fuses with

```
avrprog.read_fuses(chip_dict)
```

Which will return a list of the four fuses [low, high, ext, lock]

Write fuses with

```
avrprog.write_fuses(chip_dict, low=0xll, high=0xhh, ext=0xee,  
lock=0xkk)
```

Only arguments that are passed in will be written, so you can choose to write one fuse, or all 4.

Verify fuses with

```
avrprog.verify_fuses(chip_dict, low=0xll, high=0xhh, ext=0xee,  
lock=0xkk)
```

Only arguments that are passed in will be verified, so you can choose to verify one fuse, or all 4.

Flash

OK this is the good part, here's how you can write and verify flash memory. Reading memory to disk is not supported yet!

```
avrprog.program_file(chip_dict, "filename.hex", verbose=True,  
verify=True)
```

This function does all the work really, give it the chip information dictionary, and the name of a file (full path is OK). If `verify` is True, it will verify each page manually after writing. This is way faster than writing the whole file and then verifying the whole file so we recommend it.

If you really want, you can also verify against a file with:

```
verify_file(chip_dict, "filename.hex", verbose=True)
```

But it will check every single byte of the flash chip, so for example, if its a sparse hex file, like most bootloaders are where only a small portion of flash is data and the rest is empty, the empty parts are still checked. So it's very slow!

EEPROM

Not supported at this time!