



# PyPortal NASA Image of the Day Viewer

Created by John Park



<https://learn.adafruit.com/pyportal-nasa-image-of-the-day-viewer>

Last updated on 2024-11-18 12:58:35 PM EST

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# Overview



SPAAAAAACE! Who doesn't want to look endlessly fascinating photos of space? !

NASA's Astronomy Picture of the Day (APOD) website provides just what the title says, a new, incredible space photo each day. Now, you can set up your PyPortal to be a dedicated viewer for these glorious images!

You'll use CircuitPython to code it, and the PyPortal library will make it simple to query the NASA Open API for the image.

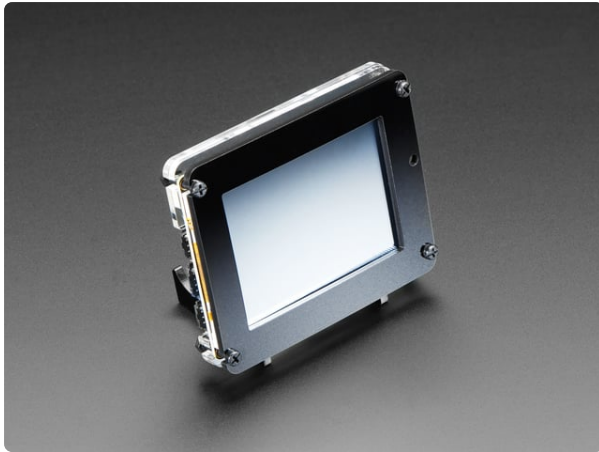
## Parts



### [Adafruit PyPortal - CircuitPython Powered Internet Display](https://www.adafruit.com/product/4116)

PyPortal, our easy-to-use IoT device that allows you to create all the things for the “Internet of Things” in minutes. Make custom touch screen interface...

<https://www.adafruit.com/product/4116>



### Adafruit PyPortal Desktop Stand Enclosure Kit

PyPortal is our easy-to-use IoT device that allows you to create all the things for the “Internet of Things” in minutes. Create little pocket...

<https://www.adafruit.com/product/4146>



### Fully Reversible Pink/Purple USB A to micro B Cable - 1m long

This cable is not only super-fashionable, with a woven pink and purple Blinka-like pattern, it's also fully reversible! That's right, you will save seconds a day by...

<https://www.adafruit.com/product/4111>

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## Install CircuitPython

CircuitPython (<https://adafru.it/tB7>) is a derivative of MicroPython (<https://adafru.it/BeZ>) designed to simplify experimentation and education on low-cost microcontrollers. It makes it easier than ever to get prototyping by requiring no upfront desktop software downloads. Simply copy and edit files on the **CIRCUITPY** "flash" drive to iterate.

The following instructions will show you how to install CircuitPython. If you've already installed CircuitPython but are looking to update it or reinstall it, the same steps work for that as well!

### Set up CircuitPython Quick Start!

Follow this quick step-by-step for super-fast Python power :)

Download the latest version of  
CircuitPython for the PyPortal via  
CircuitPython.org

<https://adafru.it/Egk>

Download the latest version of  
CircuitPython for the PyPortal PynT  
via CircuitPython.org

<https://adafru.it/HFd>

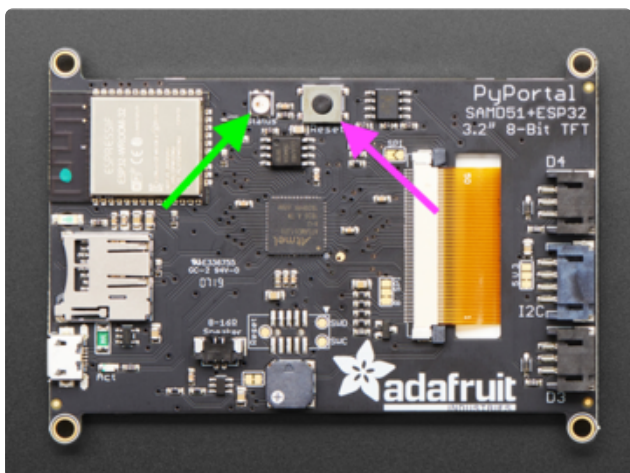


Click the link above to download the latest version of CircuitPython for the PyPortal.

Download and save it to your desktop (or wherever is handy).

Plug your PyPortal into your computer using a known-good USB cable.

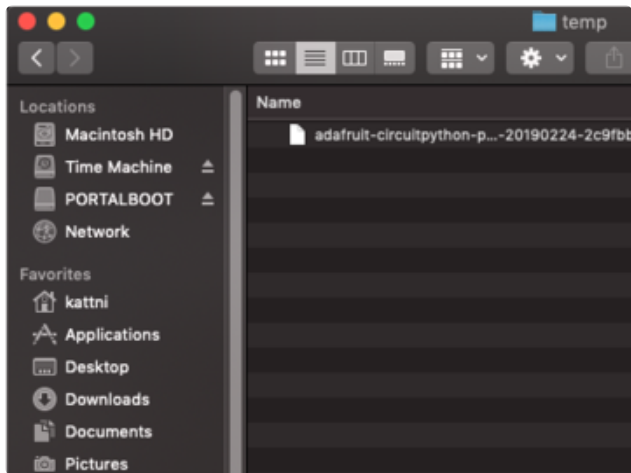
A lot of people end up using charge-only USB cables and it is very frustrating! So make sure you have a USB cable you know is good for data sync.



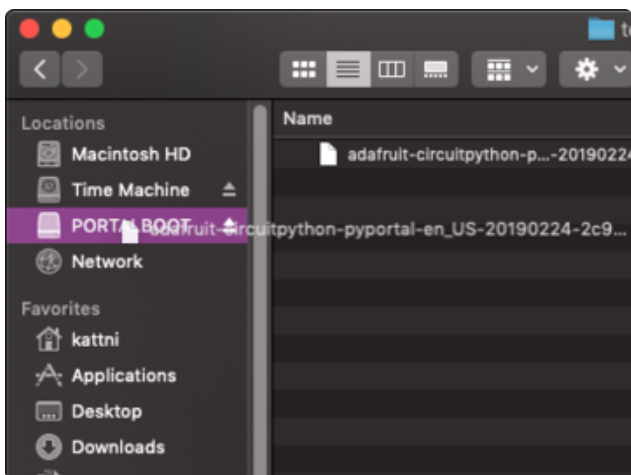
Double-click the **Reset** button on the top in the middle (magenta arrow) on your board, and you will see the NeoPixel RGB LED (green arrow) turn green. If it turns red, check the USB cable, try another USB port, etc. **Note:** The little red LED next to the USB connector will pulse red. That's ok!

If double-clicking doesn't work the first time, try again. Sometimes it can take a few tries to get the rhythm right!

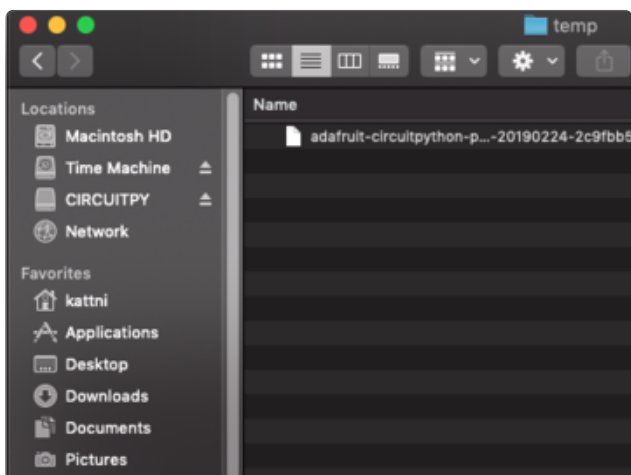




You will see a new disk drive appear called **PORTALBOOT**.



Drag the **adafruit-circuitpython-pyportal-<whatever>.uf2** file to **PORTALBOOT**.



The LED will flash. Then, the **PORTALBOOT** drive will disappear and a new disk drive called **CIRCUITPY** will appear.

If you haven't added any code to your board, the only file that will be present is **boot\_out.txt**. This is absolutely normal! It's time for you to add your **code.py** and get started!

That's it, you're done! :)

## PyPortal Default Files

Click below to download a zip of the files that shipped on the PyPortal or PyPortal Pynt.

**PyPortal Default Files**

<https://adafru.it/UF->

---

## PyPortal CircuitPython Setup

To use all the amazing features of your PyPortal with CircuitPython, you must first install a number of libraries. This page covers that process.

### Adafruit CircuitPython Bundle

Download the Adafruit CircuitPython Library Bundle. You can find the latest release here:

Latest Adafruit CircuitPython  
Library Bundle

<https://adafru.it/ENC>

Download the **adafruit-circuitpython-bundle-\*.x-mpy-\*.zip** bundle zip file where **\*.x MATCHES THE VERSION OF CIRCUITPYTHON YOU INSTALLED**, and unzip a folder of the same name. Inside you'll find a **lib** folder. You have two options:

- You can add the **lib** folder to your **CIRCUITPY** drive. This will ensure you have all the drivers. But it will take a bunch of space on the 8 MB disk
- Add each library as you need it, this will reduce the space usage but you'll need to put in a little more effort.

At a minimum we recommend the following libraries, in fact we more than recommend. They're basically required. So grab them and install them into **CIRCUITPY/lib** now!

- **adafruit\_esp32spi** - This is the library that gives you internet access via the ESP32 using (you guessed it!) SPI transport. You need this for anything Internet
- **adafruit\_requests** - This library allows us to perform HTTP requests and get responses back from servers. GET/POST/PUT/PATCH - they're all in here!
- **adafruit\_connection\_manager** - used by **adafruit\_requests**.
- **adafruit\_pyportal** - This is our friendly wrapper library that does a lot of our projects, displays graphics and text, fetches data from the internet. Nearly all of our projects depend on it!
- **adafruit\_portalbase** - This library is the base library that **adafruit\_pyportal** library is built on top of.

- **adafruit\_touchscreen** - a library for reading touches from the resistive touchscreen. Handles all the analog noodling, rotation and calibration for you.
- **adafruit\_io** - this library helps connect the PyPortal to our free datalogging and viewing service
- **adafruit\_imageload** - an image display helper, required for any graphics!
- **adafruit\_display\_text** - not surprisingly, it displays text on the screen
- **adafruit\_bitmap\_font** - we have fancy font support, and its easy to make new fonts. This library reads and parses font files.
- **adafruit\_slideshow** - for making image slideshows - handy for quick display of graphics and sound
- **neopixel** - for controlling the onboard neopixel
- **adafruit\_adt7410** - library to read the temperature from the on-board Analog Devices ADT7410 precision temperature sensor (not necessary for Titano or Pynt)
- **adafruit\_bus\_device** - low level support for I2C/SPI
- **adafruit\_fakerequests** - This library allows you to create fake HTTP requests by using local files.

---

## Create Your settings.toml File

CircuitPython works with WiFi-capable boards to enable you to make projects that have network connectivity. This means working with various passwords and API keys. As of [CircuitPython 8 \(https://adafru.it/Em8\)](https://adafru.it/Em8), there is support for a **settings.toml** file. This is a file that is stored on your **CIRCUITPY** drive, that contains all of your secret network information, such as your SSID, SSID password and any API keys for IoT services. It is designed to separate your sensitive information from your **code.py** file so you are able to share your code without sharing your credentials.

CircuitPython previously used a **secrets.py** file for this purpose. The **settings.toml** file is quite similar.

Your settings.toml file should be stored in the main directory of your CIRCUITPY drive. It should not be in a folder.

### CircuitPython settings.toml File

This section will provide a couple of examples of what your **settings.toml** file should look like, specifically for CircuitPython WiFi projects in general.



The most minimal **settings.toml** file must contain your WiFi SSID and password, as that is the minimum required to connect to WiFi. Copy this example, paste it into your **settings.toml**, and update:

- `your_wifi_ssid`
- `your_wifi_password`

```
CIRCUITPY_WIFI_SSID = "your_wifi_ssid"
CIRCUITPY_WIFI_PASSWORD = "your_wifi_password"
```

Many CircuitPython network-connected projects on the Adafruit Learn System involve using Adafruit IO. For these projects, you must also include your Adafruit IO username and key. Copy the following example, paste it into your **settings.toml** file, and update:

- `your_wifi_ssid`
- `your_wifi_password`
- `your_aio_username`
- `your_aio_key`

```
CIRCUITPY_WIFI_SSID = "your_wifi_ssid"
CIRCUITPY_WIFI_PASSWORD = "your_wifi_password"
ADAFRUIT_AIO_USERNAME = "your_aio_username"
ADAFRUIT_AIO_KEY = "your_aio_key"
```

Some projects use different variable names for the entries in the **settings.toml** file. For example, a project might use `ADAFRUIT_AIO_ID` in the place of `ADAFRUIT_AIO_USERNAME`. If you run into connectivity issues, one of the first things to check is that the names in the **settings.toml** file match the names in the code.

Not every project uses the same variable name for each entry in the **settings.toml** file! Always verify it matches the code.

## settings.toml File Tips

Here is an example **settings.toml** file.

```
# Comments are supported
CIRCUITPY_WIFI_SSID = "guest wifi"
CIRCUITPY_WIFI_PASSWORD = "guessable"
CIRCUITPY_WEB_API_PORT = 80
CIRCUITPY_WEB_API_PASSWORD = "passw0rd"
```

```
test_variable = "this is a test"
thumbs_up = "\U0001f44d"
```

In a **settings.toml** file, it's important to keep these factors in mind:

- Strings are wrapped in double quotes; ex: **"your-string-here"**
- Integers are **not** quoted and may be written in decimal with optional sign ( **+1** , **-1** , **1000** ) or hexadecimal ( **0xabcd** ).
  - Floats, octal ( **0o567** ) and binary ( **0b11011** ) are not supported.
- Use **\u** escapes for weird characters, **\x** and **\ooo** escapes are not available in **.toml** files
  - Example: **\U0001f44d** for (thumbs up emoji) and **\u20ac** for € (EUR sign)
- Unicode emoji, and non-ASCII characters, stand for themselves as long as you're careful to save in "UTF-8 without BOM" format



When your **settings.toml** file is ready, you can save it in your text editor with the **.toml** extension.

## Accessing Your **settings.toml** Information in **code.py**

In your **code.py** file, you'll need to **import** the **os** library to access the **settings.toml** file. Your settings are accessed with the **os.getenv()** function. You'll pass your settings entry to the function to import it into the **code.py** file.

```
import os
print(os.getenv("test_variable"))
```

```
CircuitPython REPL
code.py output:
this is a test

Code done running.

Press any key to enter the REPL. Use CTRL-D to reload.
```

In the upcoming CircuitPython WiFi examples, you'll see how the **settings.toml** file is used for connecting to your SSID and accessing your API keys.

---

## Internet Connect!

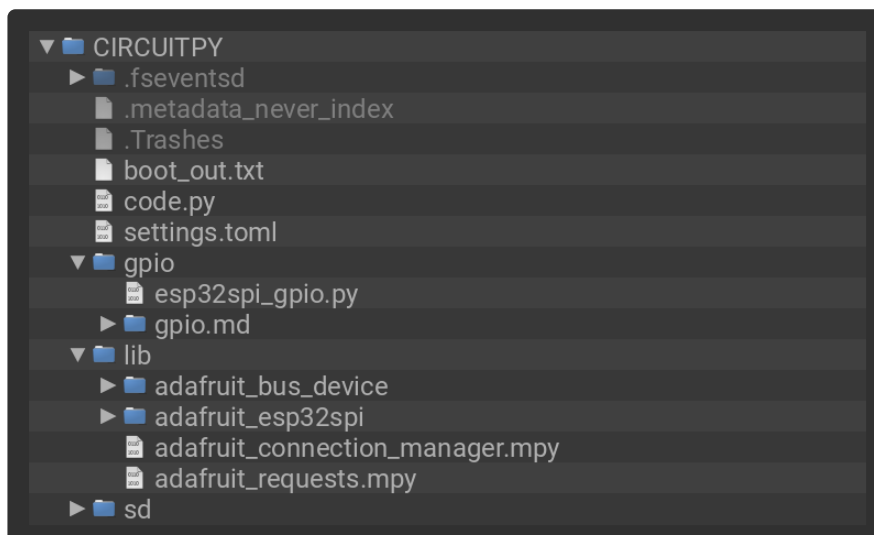
### Connect to WiFi

OK, now that you have your **settings.toml** file set up - you can connect to the Internet.

To do this, you need to first install a few libraries, into the lib folder on your **CIRCUITPY** drive. Then you need to update **code.py** with the example script.

Thankfully, we can do this in one go. In the example below, click the **Download Project Bundle** button below to download the necessary libraries and the **code.py** file in a zip file. Extract the contents of the zip file, open the directory **examples/** and then click on the directory that matches the version of CircuitPython you're using and copy the contents of that directory to your **CIRCUITPY** drive.

Your **CIRCUITPY** drive should now look similar to the following image:



If you are using CircuitPython 9.0.x on a board with frozen libraries, such the Matrix Portal M4, use this version of the "Internet Connect" program. If you are using CircuitPython 9.1.0 or later, use the second version below.

```
# SPDX-FileCopyrightText: 2019 ladyada for Adafruit Industries
# SPDX-License-Identifier: MIT

from os import getenv
import board
import busio
from digitalio import DigitalInOut
import adafruit_connection_manager
import adafruit_requests
from adafruit_esp32spi import adafruit_esp32spi

# Get wifi details and more from a settings.toml file
# tokens used by this Demo: CIRCUITPY_WIFI_SSID, CIRCUITPY_WIFI_PASSWORD
secrets = {
    "ssid": getenv("CIRCUITPY_WIFI_SSID"),
    "password": getenv("CIRCUITPY_WIFI_PASSWORD"),
}
if secrets == {"ssid": None, "password": None}:
    try:
        # Fallback on secrets.py until depreciation is over and option is removed
        from secrets import secrets
    except ImportError:
        print("WiFi secrets are kept in settings.toml, please add them there!")
        raise

print("ESP32 SPI webclient test")

TEXT_URL = "http://wifitest.adafruit.com/testwifi/index.html"
JSON_URL = "http://api.coindesk.com/v1/bpi/currentprice/USD.json"

# If you are using a board with pre-defined ESP32 Pins:
esp32_cs = DigitalInOut(board.ESP_CS)
esp32_ready = DigitalInOut(board.ESP_BUSY)
esp32_reset = DigitalInOut(board.ESP_RESET)

# If you have an AirLift Shield:
# esp32_cs = DigitalInOut(board.D10)
# esp32_ready = DigitalInOut(board.D7)
# esp32_reset = DigitalInOut(board.D5)

# If you have an AirLift Featherwing or ItsyBitsy AirLift:
# esp32_cs = DigitalInOut(board.D13)
# esp32_ready = DigitalInOut(board.D11)
# esp32_reset = DigitalInOut(board.D12)

# If you have an externally connected ESP32:
# NOTE: You may need to change the pins to reflect your wiring
# esp32_cs = DigitalInOut(board.D9)
# esp32_ready = DigitalInOut(board.D10)
# esp32_reset = DigitalInOut(board.D5)

# Secondary (SCK1) SPI used to connect to WiFi board on Arduino Nano Connect RP2040
if "SCK1" in dir(board):
    spi = busio.SPI(board.SCK1, board.MOSI1, board.MISO1)
else:
    spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
esp = adafruit_esp32spi.ESP_SPIcontrol(spi, esp32_cs, esp32_ready, esp32_reset)
```

```

pool = adafruit_connection_manager.get_radio_socketpool(esp)
ssl_context = adafruit_connection_manager.get_radio_ssl_context(esp)
requests = adafruit_requests.Session(pool, ssl_context)

if esp.status == adafruit_esp32spi.WL_IDLE_STATUS:
    print("ESP32 found and in idle mode")
print("Firmware vers.", esp.firmware_version.decode("utf-8"))
print("MAC addr:", ":".join("%02X" % byte for byte in esp.MAC_address))

for ap in esp.scan_networks():
    print("\t%-23s RSSI: %d" % (str(ap["ssid"], "utf-8"), ap["rssi"]))

print("Connecting to AP...")
while not esp.is_connected:
    try:
        esp.connect_AP(secrets["ssid"], secrets["password"])
    except OSError as e:
        print("could not connect to AP, retrying: ", e)
        continue
print("Connected to", str(esp.ssid, "utf-8"), "\tRSSI:", esp.rssi)
print("My IP address is", esp.pretty_ip(esp.ip_address))
print(
    "IP lookup adafruit.com: %s" %
    esp.pretty_ip(esp.get_host_by_name("adafruit.com"))
)
print("Ping google.com: %d ms" % esp.ping("google.com"))

# esp._debug = True
print("Fetching text from", TEXT_URL)
r = requests.get(TEXT_URL)
print("-" * 40)
print(r.text)
print("-" * 40)
r.close()

print()
print("Fetching json from", JSON_URL)
r = requests.get(JSON_URL)
print("-" * 40)
print(r.json())
print("-" * 40)
r.close()

print("Done!")

```

If you are using CircuitPython 9.1.0, or using the latest version of the ESP32SPI library, using the version below. If you are using CircuitPython 9.0.x on a board with frozen libraries, such as the Matrix Portal M4, use the first version above.

```

# SPDX-FileCopyrightText: 2019 ladyada for Adafruit Industries
# SPDX-License-Identifier: MIT

from os import getenv
import board
import busio
from digitalio import DigitalInOut
import adafruit_connection_manager
import adafruit_requests
from adafruit_esp32spi import adafruit_esp32spi

```

```

# Get wifi details and more from a settings.toml file
# tokens used by this Demo: CIRCUITPY_WIFI_SSID, CIRCUITPY_WIFI_PASSWORD
secrets = {
    "ssid": getenv("CIRCUITPY_WIFI_SSID"),
    "password": getenv("CIRCUITPY_WIFI_PASSWORD"),
}
if secrets == {"ssid": None, "password": None}:
    try:
        # Fallback on secrets.py until depreciation is over and option is removed
        from secrets import secrets
    except ImportError:
        print("WiFi secrets are kept in settings.toml, please add them there!")
        raise

print("ESP32 SPI webclient test")

TEXT_URL = "http://wifitest.adafruit.com/testwifi/index.html"
JSON_URL = "http://api.coindesk.com/v1/bpi/currentprice/USD.json"

# If you are using a board with pre-defined ESP32 Pins:
esp32_cs = DigitalInOut(board.ESP_CS)
esp32_ready = DigitalInOut(board.ESP_BUSY)
esp32_reset = DigitalInOut(board.ESP_RESET)

# If you have an AirLift Shield:
# esp32_cs = DigitalInOut(board.D10)
# esp32_ready = DigitalInOut(board.D7)
# esp32_reset = DigitalInOut(board.D5)

# If you have an AirLift Featherwing or ItsyBitsy AirLift:
# esp32_cs = DigitalInOut(board.D13)
# esp32_ready = DigitalInOut(board.D11)
# esp32_reset = DigitalInOut(board.D12)

# If you have an externally connected ESP32:
# NOTE: You may need to change the pins to reflect your wiring
# esp32_cs = DigitalInOut(board.D9)
# esp32_ready = DigitalInOut(board.D10)
# esp32_reset = DigitalInOut(board.D5)

# Secondary (SCK1) SPI used to connect to WiFi board on Arduino Nano Connect RP2040
if "SCK1" in dir(board):
    spi = busio.SPI(board.SCK1, board.MOSI1, board.MISO1)
else:
    spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
esp = adafruit_esp32spi.ESP_SPIcontrol(spi, esp32_cs, esp32_ready, esp32_reset)

pool = adafruit_connection_manager.get_radio_socketpool(esp)
ssl_context = adafruit_connection_manager.get_radio_ssl_context(esp)
requests = adafruit_requests.Session(pool, ssl_context)

if esp.status == adafruit_esp32spi.WL_IDLE_STATUS:
    print("ESP32 found and in idle mode")
print("Firmware vers.", esp.firmware_version)
print("MAC addr:", ":".join("%02X" % byte for byte in esp.MAC_address))

for ap in esp.scan_networks():
    print("\t%-23s RSSI: %d" % (ap.ssid, ap.rssi))

print("Connecting to AP...")
while not esp.is_connected:
    try:
        esp.connect_AP(secrets["ssid"], secrets["password"])
    except OSError as e:
        print("could not connect to AP, retrying: ", e)
        continue
print("Connected to", esp.ap_info.ssid, "\tRSSI:", esp.ap_info.rssi)
print("My IP address is", esp.ipv4_address)

```



```

print(
    "IP lookup adafruit.com: %s" %
    esp.pretty_ip(esp.get_host_by_name("adafruit.com"))
)
print("Ping google.com: %d ms" % esp.ping("google.com"))

# esp._debug = True
print("Fetching text from", TEXT_URL)
r = requests.get(TEXT_URL)
print("-" * 40)
print(r.text)
print("-" * 40)
r.close()

print()
print("Fetching json from", JSON_URL)
r = requests.get(JSON_URL)
print("-" * 40)
print(r.json())
print("-" * 40)
r.close()

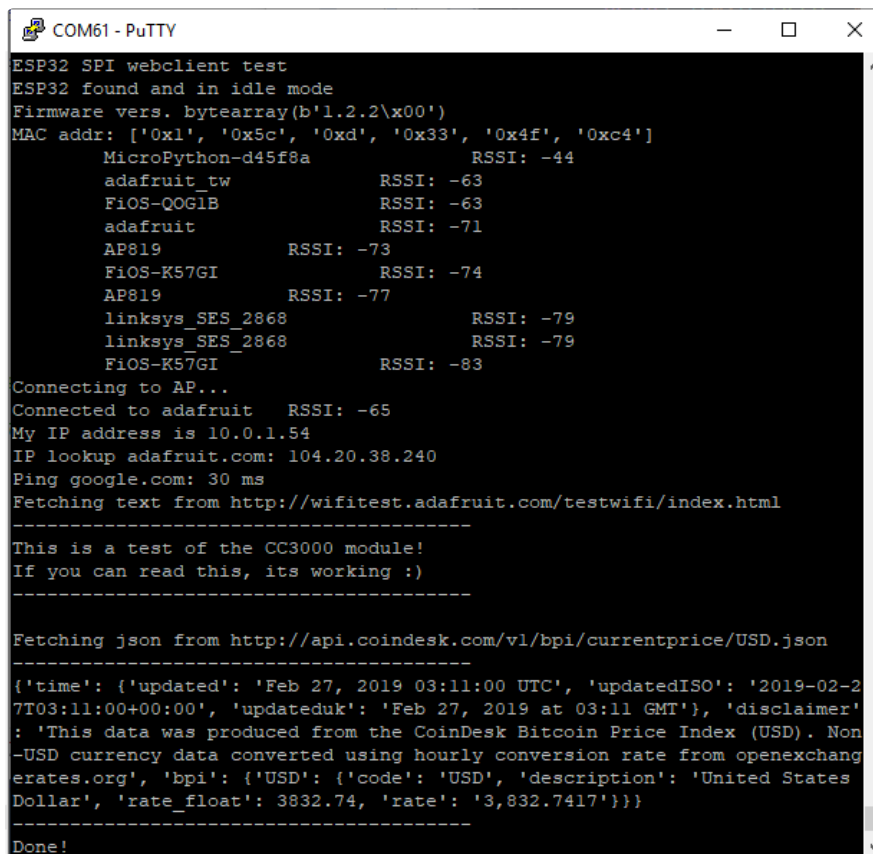
print("Done!")

```

And save it to your board, with the name **code.py**.

Don't forget you'll also need to create the **settings.toml** file as seen above, with your WiFi ssid and password.

In a serial console, you should see something like the following. For more information about connecting with a serial console, view the guide [Connecting to the Serial Console \(https://adafru.it/Bec\)](https://adafru.it/Bec).



```

COM61 - PuTTY
ESP32 SPI webclient test
ESP32 found and in idle mode
Firmware vers. bytearray(b'1.2.2\x00')
MAC addr: ['0x1', '0x5c', '0xd', '0x33', '0x4f', '0xc4']
MicroPython-d45f8a          RSSI: -44
adafruit_tw                 RSSI: -63
FiOS-QOGLB                  RSSI: -63
adafruit                    RSSI: -71
AP819                       RSSI: -73
FiOS-K57GI                  RSSI: -74
AP819                       RSSI: -77
linksys_SES_2868            RSSI: -79
linksys_SES_2868            RSSI: -79
FiOS-K57GI                  RSSI: -83
Connecting to AP...
Connected to adafruit      RSSI: -65
My IP address is 10.0.1.54
IP lookup adafruit.com: 104.20.38.240
Ping google.com: 30 ms
Fetching text from http://wifitest.adafruit.com/testwifi/index.html
-----
This is a test of the CC3000 module!
If you can read this, its working :)
-----
Fetching json from http://api.coindesk.com/v1/bpi/currentprice/USD.json
-----
{'time': {'updated': 'Feb 27, 2019 03:11:00 UTC', 'updatedISO': '2019-02-27T03:11:00+00:00', 'updateduk': 'Feb 27, 2019 at 03:11 GMT'}, 'disclaimer': 'This data was produced from the CoinDesk Bitcoin Price Index (USD). Non-USD currency data converted using hourly conversion rate from openexchangerates.org', 'bpi': {'USD': {'code': 'USD', 'description': 'United States Dollar', 'rate_float': 3832.74, 'rate': '3,832.7417'}}}
-----
Done!

```

In order, the example code...

Initializes the ESP32 over SPI using the SPI port and 3 control pins:

```
esp32_cs = DigitalInOut(board.ESP_CS)
esp32_ready = DigitalInOut(board.ESP_BUSY)
esp32_reset = DigitalInOut(board.ESP_RESET)

#...

else:
    spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
    esp = adafruit_esp32spi.ESP_SPIcontrol(spi, esp32_cs, esp32_ready, esp32_reset)
```

Gets the socket pool and the SSL context, and then tells the `adafruit_requests` library about them.

```
pool = adafruit_connection_manager.get_radio_socketpool(esp)
ssl_context = adafruit_connection_manager.get_radio_ssl_context(esp)
requests = adafruit_requests.Session(pool, ssl_context)
```

Verifies an ESP32 is found, checks the firmware and MAC address

```
if esp.status == adafruit_esp32spi.WL_IDLE_STATUS:
    print("ESP32 found and in idle mode")
print("Firmware vers.", esp.firmware_version)
print("MAC addr:", [hex(i) for i in esp.MAC_address])
```

Performs a scan of all access points it can see and prints out the name and signal strength:

```
for ap in esp.scan_networks():
    print("\t%s\t\tRSSI: %d" % (str(ap['ssid'], 'utf-8'), ap['rssi']))
```

Connects to the AP we've defined here, then prints out the local IP address, attempts to do a domain name lookup and ping google.com to check network connectivity (note sometimes the ping fails or takes a while, this isn't a big deal)

```
print("Connecting to AP...")
while not esp.is_connected:
    try:
        esp.connect_AP(secrets["ssid"], secrets["password"])
    except RuntimeError as e:
        print("could not connect to AP, retrying: ", e)
        continue
print("Connected to", str(esp.ssid, "utf-8"), "\tRSSI:", esp.rssi)
print("My IP address is", esp.pretty_ip(esp.ip_address))
print(
    "IP lookup adafruit.com: %s" %
    esp.pretty_ip(esp.get_host_by_name("adafruit.com")))
```

OK now we're getting to the really interesting part. With a SAMD51 or other large-RAM (well, over 32 KB) device, we can do a lot of neat tricks. Like for example we can implement an interface a lot like [requests](https://adafru.it/E9o) (<https://adafru.it/E9o>) - which makes getting data really really easy

To read in all the text from a web URL call `requests.get` - you can pass in `https` URLs for SSL connectivity

```
TEXT_URL = "http://wifitest.adafruit.com/testwifi/index.html"
print("Fetching text from", TEXT_URL)
r = requests.get(TEXT_URL)
print('- '*40)
print(r.text)
print('- '*40)
r.close()
```

Or, if the data is in structured JSON, you can get the json pre-parsed into a Python dictionary that can be easily queried or traversed. (Again, only for nRF52840, M4 and other high-RAM boards)

```
JSON_URL = "http://api.coindesk.com/v1/bpi/currentprice/USD.json"
print("Fetching json from", JSON_URL)
r = requests.get(JSON_URL)
print('- '*40)
print(r.json())
print('- '*40)
r.close()
```

## Requests

We've written a [requests-like](https://adafru.it/Kpa) (<https://adafru.it/Kpa>) library for web interfacing named [Adafruit\\_CircuitPython\\_Requests](https://adafru.it/FpW) (<https://adafru.it/FpW>). This library allows you to send HTTP/1.1 requests without "crafting" them and provides helpful methods for parsing the response from the server.

To use with CircuitPython, you need to first install a few libraries, into the lib folder on your **CIRCUITPY** drive. Then you need to update `code.py` with the example script.

Thankfully, we can do this in one go. In the example below, click the **Download Project Bundle** button below to download the necessary libraries and the `code.py` file in a zip file. Extract the contents of the zip file, open the directory `examples/` and then click on the directory that matches the version of CircuitPython you're using and copy the contents of that directory to your **CIRCUITPY** drive.

Your **CIRCUITPY** drive should now look similar to the following image:

CIRCUITPY

Temporarily unable to load content:

The code first sets up the ESP32SPI interface. Then, it initializes a `request` object using an ESP32 `socket` and the `esp` object.

```
import board
import busio
from digitalio import DigitalInOut
import adafruit_esp32spi.adafruit_esp32spi_socket as socket
from adafruit_esp32spi import adafruit_esp32spi
import adafruit_connection_manager
import adafruit_requests as requests

# If you are using a board with pre-defined ESP32 Pins:
esp32_cs = DigitalInOut(board.ESP_CS)
esp32_ready = DigitalInOut(board.ESP_BUSY)
esp32_reset = DigitalInOut(board.ESP_RESET)

# If you have an externally connected ESP32:
# esp32_cs = DigitalInOut(board.D9)
# esp32_ready = DigitalInOut(board.D10)
# esp32_reset = DigitalInOut(board.D5)

spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
esp = adafruit_esp32spi.ESP_SPIcontrol(spi, esp32_cs, esp32_ready, esp32_reset)

print("Connecting to AP...")
while not esp.is_connected:
    try:
        esp.connect_AP(b'MY_SSID_NAME', b'MY_SSID_PASSWORD')
    except RuntimeError as e:
        print("could not connect to AP, retrying: ",e)
        continue
print("Connected to", str(esp.ssid, 'utf-8'), "\tRSSI:", esp.rssi)

pool = adafruit_connection_manager.get_radio_socketpool(esp)
ssl_context = adafruit_connection_manager.get_radio_ssl_context(esp)
requests = adafruit_requests.Session(pool, ssl_context)
```

## HTTP GET with Requests

The code makes a HTTP GET request to Adafruit's WiFi testing website - <http://wifitest.adafruit.com/testwifi/index.html> (<https://adafru.it/Fp->).

To do this, we'll pass the URL into `requests.get()`. We're also going to save the response from the server into a variable named `response`.

Having requested data from the server, we'd now like to see what the server responded with. Since we already saved the server's `response`, we can read it back. Luckily for us, `requests` automatically decodes the server's response into human-readable text, you can read it back by calling `response.text`.

Lastly, we'll perform a bit of cleanup by calling `response.close()`. This closes, deletes, and collect's the response's data.

```
print("Fetching text from %s"%TEXT_URL)
response = requests.get(TEXT_URL)
print('- '*40)

print("Text Response: ", response.text)
print('- '*40)
response.close()
```

While some servers respond with text, some respond with json-formatted data consisting of attribute–value pairs.

**CircuitPython\_Requests** can convert a **JSON**-formatted response from a server into a CPython **dict.** object.

We can also fetch and parse **json** data. We'll send a HTTP get to a url we know returns a json-formatted response (instead of text data).

Then, the code calls **response.json()** to convert the response to a CPython **dict.**

```
print("Fetching JSON data from %s"%JSON_GET_URL)
response = requests.get(JSON_GET_URL)
print('- '*40)

print("JSON Response: ", response.json())
print('- '*40)
response.close()
```

## HTTP POST with Requests

Requests can also **POST** data to a server by calling the **requests.post** method, passing it a **data** value.

```
data = '31F'
print("POSTing data to {0}: {1}".format(JSON_POST_URL, data))
response = requests.post(JSON_POST_URL, data=data)
print('- '*40)

json_resp = response.json()
# Parse out the 'data' key from json_resp dict.
print("Data received from server:", json_resp['data'])
print('- '*40)
response.close()
```

You can also post json-formatted data to a server by passing **json\_data** into the **requests.post** method.

```
json_data = {"Date" : "July 25, 2019"}
print("POSTing data to {0}: {1}".format(JSON_POST_URL, json_data))
response = requests.post(JSON_POST_URL, json=json_data)
print('- '*40)

json_resp = response.json()
# Parse out the 'json' key from json_resp dict.
```

```
print("JSON Data received from server:", json_resp['json'])
print('- '*40)
response.close()
```

## Advanced Requests Usage

Want to send custom HTTP headers, parse the response as raw bytes, or handle a response's http status code in your CircuitPython code?

We've written an example to show advanced usage of the requests module below.

To use with CircuitPython, you need to first install a few libraries, into the lib folder on your **CIRCUITPY** drive. Then you need to update **code.py** with the example script.

Thankfully, we can do this in one go. In the example below, click the **Download Project Bundle** button below to download the necessary libraries and the **code.py** file in a zip file. Extract the contents of the zip file, open the directory **examples/** and then click on the directory that matches the version of CircuitPython you're using and copy the contents of that directory to your **CIRCUITPY** drive.

Your **CIRCUITPY** drive should now look similar to the following image:

CIRCUITPY

Temporarily unable to load content:

## WiFi Manager

That simplest example works but it's a little finicky - you need to constantly check WiFi status and have many loops to manage connections and disconnections. For more advanced uses, we recommend using the WiFiManager object. It will wrap the connection/status/requests loop for you - reconnecting if WiFi drops, resetting the ESP32 if it gets into a bad state, etc.

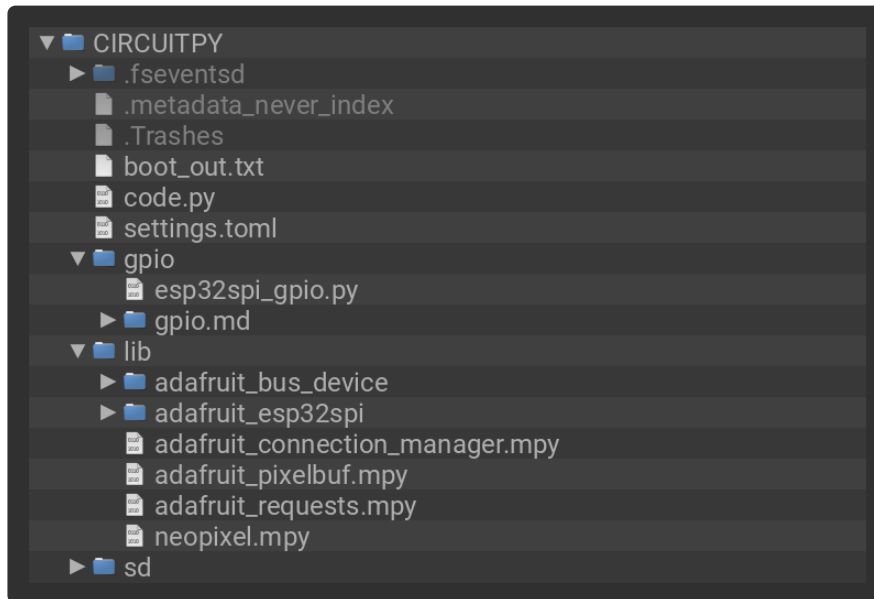
Here's a more advanced example that shows the WiFi manager and also how to POST data with some extra headers:

To use with CircuitPython, you need to first install a few libraries, into the lib folder on your **CIRCUITPY** drive. Then you need to update **code.py** with the example script.

Thankfully, we can do this in one go. In the example below, click the **Download Project Bundle** button below to download the necessary libraries and the **code.py** file in a zip file. Extract the contents of the zip file, open the directory **examples/** and then click on the directory that matches the version of CircuitPython you're using and copy the contents of that directory to your **CIRCUITPY** drive.



Your **CIRCUITPY** drive should now look similar to the following image:



```
# SPDX-FileCopyrightText: 2019 ladyada for Adafruit Industries
# SPDX-License-Identifier: MIT

import time
from os import getenv
import board
import busio
from digitalio import DigitalInOut
import neopixel
from adafruit_esp32spi import adafruit_esp32spi
from adafruit_esp32spi import adafruit_esp32spi_wifimanager

print("ESP32 SPI webclient test")

# Get wifi details and more from a settings.toml file
# tokens used by this Demo: CIRCUITPY_WIFI_SSID, CIRCUITPY_WIFI_PASSWORD
#                               CIRCUITPY_AIO_USERNAME, CIRCUITPY_AIO_KEY
secrets = {}
for token in ["ssid", "password"]:
    if getenv("CIRCUITPY_WIFI_" + token.upper()):
        secrets[token] = getenv("CIRCUITPY_WIFI_" + token.upper())
for token in ["aio_username", "aio_key"]:
    if getenv("CIRCUITPY_" + token.upper()):
        secrets[token] = getenv("CIRCUITPY_" + token.upper())

if not secrets:
    try:
        # Fallback on secrets.py until depreciation is over and option is removed
        from secrets import secrets
    except ImportError:
        print("WiFi secrets are kept in settings.toml, please add them there!")
        raise

# If you are using a board with pre-defined ESP32 Pins:
esp32_cs = DigitalInOut(board.ESP_CS)
esp32_ready = DigitalInOut(board.ESP_BUSY)
esp32_reset = DigitalInOut(board.ESP_RESET)

# If you have an externally connected ESP32:
# esp32_cs = DigitalInOut(board.D9)
# esp32_ready = DigitalInOut(board.D10)
# esp32_reset = DigitalInOut(board.D5)
```

```

# Secondary (SCK1) SPI used to connect to WiFi board on Arduino Nano Connect RP2040
if "SCK1" in dir(board):
    spi = busio.SPI(board.SCK1, board.MOSI1, board.MISO1)
else:
    spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
esp = adafruit_esp32spi.ESP_SPIcontrol(spi, esp32_cs, esp32_ready, esp32_reset)
"""Use below for Most Boards"""
status_light = neopixel.NeoPixel(board.NEOPIXEL, 1, brightness=0.2)
"""Uncomment below for ItsyBitsy M4"""
# status_light = dotstar.DotStar(board.APA102_SCK, board.APA102_MOSI, 1,
# brightness=0.2)
"""Uncomment below for an externally defined RGB LED (including Arduino Nano
Connect)"""
# import adafruit_rgbled
# from adafruit_esp32spi import PWMOut
# RED_LED = PWMOut.PWMOut(esp, 26)
# GREEN_LED = PWMOut.PWMOut(esp, 27)
# BLUE_LED = PWMOut.PWMOut(esp, 25)
# status_light = adafruit_rgbled.RGBLED(RED_LED, BLUE_LED, GREEN_LED)

wifi = adafruit_esp32spi_wifimanager.ESPSPI_WiFiManager(esp, secrets, status_light)

counter = 0

while True:
    try:
        print("Posting data...", end="")
        data = counter
        feed = "test"
        payload = {"value": data}
        response = wifi.post(
            "https://io.adafruit.com/api/v2/"
            + secrets["aio_username"]
            + "/feeds/"
            + feed
            + "/data",
            json=payload,
            headers={"X-AIO-KEY": secrets["aio_key"]},
        )
        print(response.json())
        response.close()
        counter = counter + 1
        print("OK")
    except OSError as e:
        print("Failed to get data, retrying\n", e)
        wifi.reset()
        continue
    response = None
    time.sleep(15)

```

You'll note here we use a secrets.py file to manage our SSID info. The wifimanager is given the ESP32 object, secrets and a neopixel for status indication.

Note, you'll need to add some additional information to your secrets file so that the code can query the Adafruit IO API:

- `aio_username`
- `aio_key`

You can go to your [adafruit.io View AIO Key](#) link to get those two values and add them to the secrets file, which will now look something like this:

```
# This file is where you keep secret settings, passwords, and tokens!
# If you put them in the code you risk committing that info or sharing it

secrets = {
    'ssid' : '_your_ssid_',
    'password' : '_your_wifi_password_',
    'timezone' : "America/Los_Angeles", # http://worldtimeapi.org/timezones
    'aio_username' : '_your_aio_username_',
    'aio_key' : '_your_aio_key_',
}
```

Next, set up an Adafruit IO feed named **test**

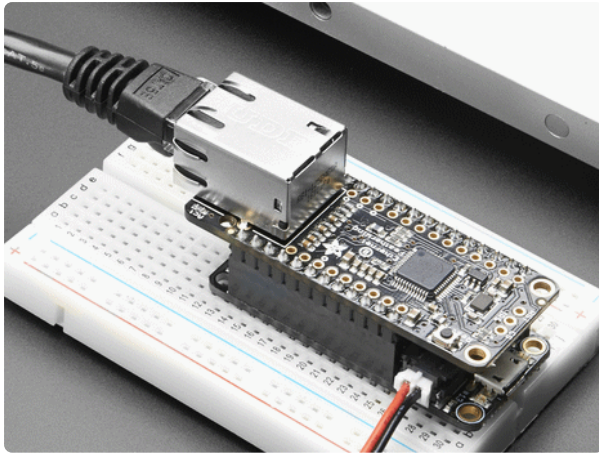
- If you do not know how to set up a feed, [follow this page and come back when you've set up a feed named \*\*test\*\*](https://adafru.it/f5k). (<https://adafru.it/f5k>)

We can then have a simple loop for posting data to Adafruit IO without having to deal with connecting or initializing the hardware!

Take a look at your **test** feed on Adafruit.io and you'll see the value increase each time the CircuitPython board posts data to it!



For more information on the basics of doing networking in CircuitPython, see this [guide](#):



## Networking in CircuitPython

By Anne Barela

<https://learn.adafruit.com/networking-in-circuitpython>

---

# Code PyPortal NASA Image Viewer



## NASA Open API Key

We'll use the NASA API to make our queries and retrieve our image of the day. In order to do so, you'll need to register for a free account with [api.nasa.gov](https://api.nasa.gov) and get your API key.

It's easy to do, just head to this [link \(https://adafru.it/EqP\)](https://adafru.it/EqP) and enter your name and email address. That's all there is to it! Your API key will be generated and sent to you via email, as well as showing up immediately in the browser. Keep that key (or the email containing it) handy, we'll need to copy and paste it into our code in a moment.

## Adafruit IO Time Server

In order to get use the Adafruit image converter, this project will require you to have an Adafruit IO username and key. Adafruit IO is absolutely free to use, but you'll need

to log in with your Adafruit account to use it. If you don't already have an Adafruit login, create [one here](https://adafru.it/dAQ) (<https://adafru.it/dAQ>).

If you haven't used Adafruit IO before, [check out this guide for more info](https://adafru.it/Ef8) (<https://adafru.it/Ef8>).

Once you have logged into your account, there are two pieces of information you'll need to place in your **settings.toml** file: **Adafruit IO username**, and **Adafruit IO key**. Head to [io.adafruit.com](https://adafru.it/fsU) (<https://adafru.it/fsU>) and simply click the **View AIO Key** link on the left hand side of the Adafruit IO page to get this information.

Then, add them to the **settings.toml** file like this:

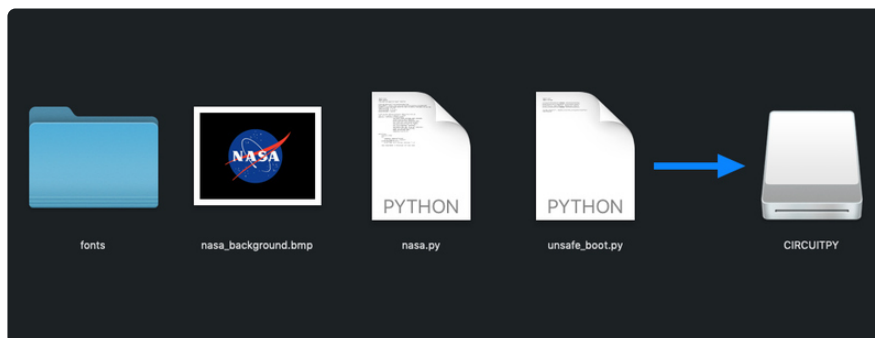
```
CIRCUITPY_WIFI_SSID = "your_wifi_ssid"
CIRCUITPY_WIFI_PASSWORD = "your_wifi_password"
AIO_USERNAME = "your_aio_username"
AIO_KEY = "your_aio_key"
```

## Add CircuitPython Code and Assets

In the [Project Code](https://adafru.it/luu) (<https://adafru.it/luu>) section further down this page, click on the **Download Project Bundle** button, and save the .zip archive file to your computer.

Then, uncompress the .zip file, it will unpack to a folder named **PyPortal\_NASA**.

Copy the contents of the **PyPortal\_NASA** directory to your PyPortal **CIRCUITPY** drive.



## Editing the Code

You can edit the **code.py** file with any text editor you like. Adafruit suggests installing the free Mu Python editor as it's super handy, recognizes Adafruit boards, and has a built in serial monitor/REPL to interact with the board. [Find out more about Mu here](https://adafru.it/ANO) (<https://adafru.it/ANO>).

## Add NASA API Key

Open up **code.py** in Mu and then copy and paste your API key from NASA that we got earlier in to the **DATA\_SOURCE** url, getting rid of the words **DEMO\_KEY** and replacing it with your actual API key.

That line will look something like this:

```
DATA_SOURCE = "https://api.nasa.gov/planetary/apod?  
api_key=your_actual_really_long_key_here"
```

When you're done, save the **code.py** file again to your PyPortal's **CIRCUITPY** drive.

## boot.py

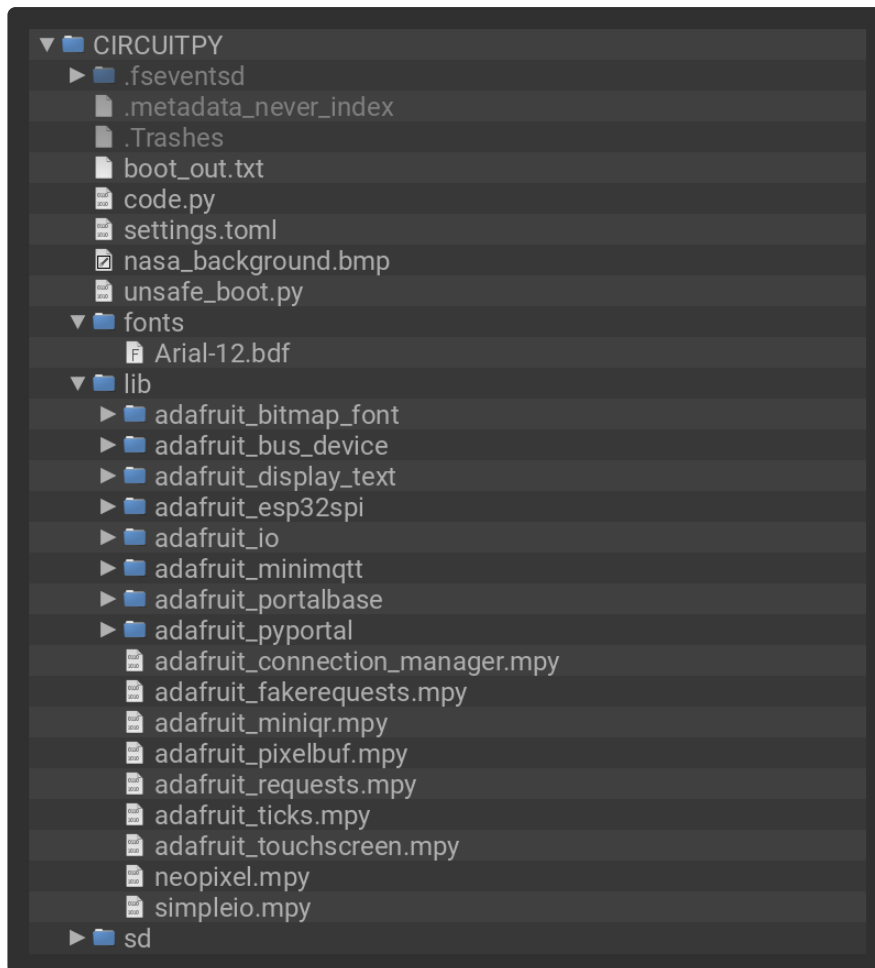
We're using a special file to ensure the .bmp cache writes to the flash properly. This is the **unsafe\_boot.py** file you copied to the drive. Rename it to **boot.py** now.

Note that you'll see this scary looking text appear during restart, don't worry, it's supposed to say that!

```
***** WARNING *****  
Using the filesystem as a write-able cache!  
This is risky behavior, backup your files!  
***** WARNING *****
```

This is what the final contents of the **CIRCUITPY** drive will look like:





## Project Code

```
# SPDX-FileCopyrightText: 2019 Limor Fried for Adafruit Industries
#
# SPDX-License-Identifier: MIT

import time
import board
from adafruit_pyportal import PyPortal

# Set up where we'll be fetching data from
DATA_SOURCE = "https://api.nasa.gov/planetary/apod?api_key=DEMO_KEY"
# There's a few different places we look for data in the photo of the day
IMAGE_LOCATION = ["url"]
TITLE_LOCATION = ["title"]
DATE_LOCATION = ["date"]

# the current working directory (where this file is)
cwd = ("/" + __file__).rsplit('/', 1)[0]
pyportal = PyPortal(url=DATA_SOURCE,
                    json_path=(TITLE_LOCATION, DATE_LOCATION),
                    status_neopixel=board.NEOPIXEL,
                    default_bg=cwd+"/nasa_background.bmp",
                    text_font=cwd+"/fonts/Arial-12.bdf",
                    text_position=((5, 220), (5, 200)),
                    text_color=(0xFFFFFF, 0xFFFFFF),
                    text_maxlen=(50, 50), # cut off characters
                    image_json_path=IMAGE_LOCATION,
                    image_resize=(320, 240),
                    image_position=(0, 0))

while True:
```

```
response = None
try:
    response = pyportal.fetch()
    print("Response is", response)
except RuntimeError as e:
    print("Some error occurred, retrying! -", e)

time.sleep(30*60) # 30 minutes till next check
```

If you run into any errors, such as "ImportError: no module named `adafruit\_display\_text.label`" be sure to update your libraries to the latest release bundle!

## How It Works

The NASA Image Viewer is doing a few cool things using CircuitPython and the PyPortal:

### Background Splash Screen

First, we'll display a splash screen with the NASA logo. This is a 320x240 pixel RGB 16-bit raster graphic in **.bmp** format.



### Font

We'll be displaying the image title and today's date as text created with a bitmapped font to overlay on top of the background image once that's loaded. The font used here is a bitmap font made from an oblique Arial typeface. You can learn more about [converting type in this guide \(https://adafru.it/E7E\)](https://adafru.it/E7E).

### JSON

In order to retrieve the NASA Astronomy Picture of the Day (APOD), we'll be making a query to the NASA API.

When you make a request of the APOD server with your API key added, you'll get a JSON file returned as the response.

In fact, you can run the same query as the PyPortal does to see the result. Copy and paste this link `https://api.nasa.gov/planetary/apod?api_key=DEMO_KEY`

into your browser, except replace DEMO\_KEY with your own API key that NASA sent in the registration email.

When you enter this in your web browser, you'll see a result returned like this:

```
{
  "copyright": "Mario Zauner",
  "date": "2019-04-03",
  "explanation": "The famous Horsehead Nebula in Orion is not alone. A deep exposure shows that the dark familiar shaped indentation, visible just below center, is part of a vast complex of absorbing dust and glowing gas. To bring out details of the Horsehead's pasture, an amateur astronomer used a backyard telescope in Austria to accumulate and artistically combine 7.5 hours of images in the light of Hydrogen (red), Oxygen (green), and Sulfur (blue). The resulting spectacular picture details an intricate tapestry of gaseous wisps and dust-laden filaments that were created and sculpted over eons by stellar winds and ancient supernovas. The Flame Nebula is visible just to the left of the Horsehead, while the bright star on the upper left is Alnilam, the central star in Orion's Belt. The Horsehead Nebula lies 1,500 light years distant towards the constellation of Orion. Bounce around the Universe: Random APOD Generator",
  "hdurl": "https://apod.nasa.gov/apod/image/1904/HorseheadFlame_Zauner_4404.jpg",
  "media_type": "image",
  "service_version": "v1",
  "title": "Wisps Surrounding the Horsehead Nebula",
  "url": "https://apod.nasa.gov/apod/image/1904/HorseheadFlame_Zauner_960.jpg"
}
```

That result is a JSON (JavaScript Object Notation) array. It is comprised of a single element with seven **key:value** pairs. For example, there is one **key** called `date` which has a **value** of `2019-04-03` which is expressed this way:

```
"date": "2019-04-03"
```

And another we care about is the `title` **key**, which has a **value** of `Wisps Surrounding the Horsehead Nebula`

So that is expressed as:

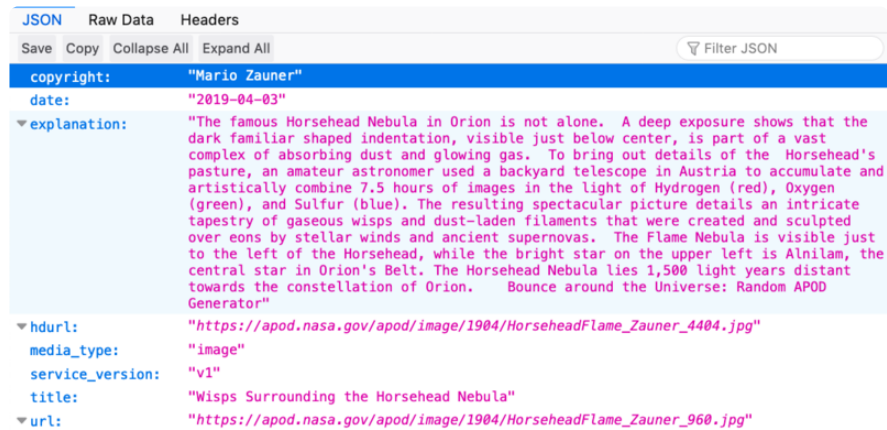
```
"title": "Wisps Surrounding the Horsehead Nebula"
```

Another **key** we really care about is the `url` which has a **value** of the image location:

```
"url": "https://apod.nasa.gov/apod/image/1904/HorseheadFlame_Zauner_960.jpg"
```

Since this JSON object array has a consistent way to return the results to us, the code we're running on the PyPortal can easily parse the data and display it!

Here's what the JSON file looks like in the "code beautifier" of Firefox.



You can see how it's done in this part of **code.py**:

```
DATA_SOURCE = "https://api.nasa.gov/planetary/apod?api_key=xxxxxxx" #put your api
key here
IMAGE_LOCATION = ["url"]
TITLE_LOCATION = ["title"]
DATE_LOCATION = ["date"]
```

Then, in the **pyportal** query we ask for the **date** and **title** names from that URL, and then use the **text\_** arguments to set the **font**, **position**, **color**, **wrap**, and **maxlen** of the text when it is displayed.

We use the **url** name to get the path to the .jpeg image file.

```
pyportal = PyPortal(url=DATA_SOURCE,
                    json_path=(TITLE_LOCATION, DATE_LOCATION),
                    status_neopixel=board.NEOPIXEL,
                    default_bg=cwd+"/nasa_background.bmp",
                    text_font=cwd+"/fonts/Arial-12.bdf",
                    text_position=((5, 220), (5, 200)),
                    text_color=(0xFFFFFF, 0xFFFFFF),
                    text_maxlen=(50, 50), # cut off characters
                    image_json_path=IMAGE_LOCATION,
                    image_resize=(320, 240),
                    image_position=(0, 0))
```

With all of this prepared, during the main loop of **while True:** the code will query the NASA page for the JSON data.

When it gets the path of the .jpeg file, the pyportal library passes it along to an Adafruit IO image converter server where the file is converted into the format the PyPortal can display, a 320x240 pixel RGB 16-bit .bmp.



This image is then cached onto the PyPortal's storage and displayed on the PyPortal TFT screen.

Finally, the text will be displayed over the image.

This updates every thirty minutes. Be aware, you cannot make more than 50 queries per day to the NASA API!



One user reported problems related to a slow internet connection, which they resolved by increasing the timeout value in the `adafruit_requests` library from 1 second up to 5 seconds.