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Overview

Yay you have finally moved on from 8-bit chips and are ready to try out some 32-bit hotness! Those ARM Cortex chips look fun, some have built in bluetooth, or 2.4ghz radios, or usb...all you have to do is learn how to program them.

OpenOCD

On your way to learning how to use your favorite new ARM Cortex you may have heard of OpenOCD (https://adafruit.it/fMy). OpenOCD is the software that we will use to do the actual programming of chips. Unlike the AVR ISP programming protocol, every ARM chip is significantly different to program, with platform-unique commands, flash locations, fuse bits, settings, etc. Teasing out those details is a struggle and if you change chips you have to start all over even if both chips are, say, Cortex-M3 based!

Each chip fab tends to supply its own programming software - Atmel has Atmel Studio, Nordic has NRFGo, ST has ST Link - but often times that software is Windows only.

OpenOCD is great because its cross platform, open source, and has support for a vast number of chips & programmers.
You can use OpenOCD with dongle-programmers such as J-Link and ST-Link or even an FTDI chip. But, if you have a spare Raspberry Pi (and who doesn't these days?) you can use it as a native OpenOCD programmer with just a few wires.

It's also really fast to program chips natively, and if you have to program a mess of chips, it can make things speedy - an extra 30 seconds adds up when you're doing 1000!

### Compiling OpenOCD

Compiling OpenOCD takes about 15 minutes but is worth the effort to get the latest code. You'll need to have command line access and a Pi on the Internet so you can download packages and software.


### Compiling OpenOCD

Start by doing a fresh sudo apt-get update this will make sure you have the latest packages and repository set up.

Next, run

```
sudo apt-get install git autoconf libtool make pkg-config libusb-1.0-0 libusb-1.0-0-dev
```

to install all the tools you'll need to compile OpenOCD. OpenOCD changes a lot and is under constant development so we do suggest compiling your own!
Download the latest source code for OpenOCD with

git clone http://openocd.zylin.com/openocd

Change into the code directory and run the bootstrapper with:

  cd openocd-code
  ./bootstrap
Next, we will compile OpenOCD with the Raspberry Pi native GPIO twiddling support - this will work on various Raspberry Pi's despite being called 'bcm2835gpio'.

```
./configure --enable-sysfsgpio --enable-bcm2835gpio
```

If you're following this guide on a non-Pi embedded linux board, you can skip the --enable-bcm2835gpio part and try to just use sysfsgpio. Sysfsgpio is much slower than native GPIO twiddling but it may not matter too much in your application.
Note that when done, it won't mention GPIO support in the configuration summary, that's OK!

Run make
Assuming compilation completes successfully as above, you can install with

```
sudo make install
```

That's pretty much it!

You can see the list of interfaces available in `/usr/local/share/openocd/scripts/interface`

There's a lot of options, in particular check out raspberrypi2-native.cfg and raspberry pi-native.cfg if you are interested in using OpenOCD with a non-Pi, look at sysfsgpio-raspberry.cfg which can help you port to a different linux computer
Wiring and Test

Connecting to Target

OK you've done the compiling, now you are ready to connect!

In this case, I'll be connecting to an Atmel ATSAMD21G18 Cortex-M0 over SWD and uploading the Arduino bootloader to it. You can, of course, connect to any processor that OpenOCD supports but this is the one I've got handy

Wire up the target to SWD

Of course connections must be made! Note that we are using the "BCM" pin numbering convention (https://adafru.it/jEa)
Connect:

- Target GND to Pi GND
- Target SWDIO to Raspberry Pi #24
- Target SWCLK to Raspberry Pi #25
- Target Reset to Raspberry Pi #18 (may not be required)
- If powering the chip directly from the Pi, connect 3.3V to 3.3V (I'm just powering the chip over USB)

Of course, this assumes that your chip is running at 3.3V logic. For 1.8 or 5V logic, level shifting may be required.

You can later change the pins used in the interfaces configuration file but for now, I suggest just going with the default

Create OpenOCD config

The easiest way to connect is creating a new directory in your home dir
cd ~
mkdir bootloader

cd bootloader

and then putting the file you want to program there, in this case I'm going to just grab the latest Arduino Zero bootloader (of course, substitute your own binary or hex!)

wget https://github.com/arduino/ArduinoCore-samd/raw/master/bootloaders/zero/samd21_sam_ba.bin

In the same directory, make a new file called openocd.cfg

nano openocd.cfg

and put the following into it:

```
source [find interface/raspberrypi2-native.cfg]
transport select swd

set CHIPNAME at91samd21g18
source [find target/at91samdXX.cfg]

# did not yet manage to make a working setup using srst
reset_config srst_only
reset_config srst_nogate

adapter_nsrst_delay 100
adapter_nsrst_assert_width 100

init
targets
reset halt
```
Change rasperrypi2-native.cfg to whatever config you are using, e.g. for a Pi Zero or 1 use rasperrypi1-native.cfg or rasperrypi-native.cfg

If you’re using a Pi Zero/1 you may also need to add

```
bcm2835gpio_sw_d_nums 25 24
bcm2835gpio_trst_num 7
bcm2835gpio_srst_num 18
```

You may need to also comment out `reset_config srst_nogate`, some people report that is required to make it work

Save the config file and then run `sudo openocd` (no other args, its all in the config!) in the directory. You should get the following indicating a good connection
In particular make sure you get that target state:halted to you know it was able to connect!

Hit control-C to cancel out of openocd.

If you get unknown for state, or other errors, check your wiring! You may also need to powercycle or disconnect parts from the chip to get it into a good programming state. You may also need to change the programming frequency.

Hit control-C to cancel out of openocd (or you can telnet 127.0.0.1 4444 if you want to send commands, won't be covered here.

Now you can change the openocd.cfg with nano to add commands for burning the binary file. At the bottom put in:

```
init
targets
reset halt
at91samd bootloader 0
program samd21_sam_ba verify
at91samd bootloader 8192
reset
shutdown
```

This will init, look for targets, reset and halt the chip, turn off bootloader protection, burn in the bootloader file and verify it, re-turn-on bootloader protection, reset and shutdown openocd.
You can skip the bootloader protection parts if you are not burning in a bootloader, of course

Of course, change the commands if you have a different file name, different chip, etc.

Save the file and run sudo openocd again:

Zoom! Programmed the bootloader in 0.02 seconds!
More Options

If you don't want to set up the configure file, you can actually do it all from the command line:

```
sudo openocd -f interface/raspberrypi2-native.cfg -c "transport select swd; set WORKAREASIZE 0; adapter_nsrst_delay 100; adapter_nsrst_assert_width 100; source [find target/nrf51.cfg]" -c "init; reset; halt; nrf51 mass_erase; reset" -c "shutdown"
```

This will, for example, erase and reset a Nordic nRF51822 (which is a pretty finicky chip by the way, you may need to do hard resets to get it to talk to openocd)