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Overview

CircuitPython MIDI
Build a MIDI drum kit using solenoids and CircuitPython! 3D print parts to create a solenoid driven mallet to trigger snare drums, cymbals and much more! Use the Adafruit Feather M4 and ULN2803A darlington driver to create your own custom USB MIDI percussion ensemble.

Plug and Play
The Feather M4 and ULN2803A darlington driver are fitted onto a Perma-Proto board housed inside a snap fit case. DC jacks on the side of the case allow for plug and play of the solenoids.

DIY Drum Kit
DIY your own cymbals, tom toms, snare and kick drum. Use the mallets to hit any surface to make programmable percussion instruments.
Modular Design
To make the kick drum, a solenoid is mounted to a piece of 2020 extrusion that hovers over a practice drum pad. This creates a direct hit and makes a nice ‘thud’.

Parts

Adafruit Feather M4 Express - Featuring ATSAMD51
It's what you've been waiting for, the Feather M4 Express featuring ATSAMD51. This Feather is fast like a swift, smart like an owl, strong like a ox-bird (it's half ox,...
https://www.adafruit.com/product/3857

Large push-pull solenoid
Solenoids are basically electromagnets: they are made of a big coil of copper wire with an armature (a slug of metal) in the middle. When the coil is energized, the slug is pulled into...
https://www.adafruit.com/product/413
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<td>DC barrel jack</td>
<td>Panel Mount 2.1mm DC barrel jack</td>
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<td>12V 5A switching power supply</td>
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<td>Feather Header Kit</td>
<td>Header Kit for Feather - 12-pin and 16-pin Female Header Set</td>
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<td>Fully Reversible Pink/Purple USB A to micro B Cable - 1m long</td>
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Customers have asked us to carry basic perf-board, but we never liked the look of most basic perf: it's always crummy quality, with pads that flake off and no labeling. Then we...

https://www.adafruit.com/product/1609

Bring in some muscle to your output pins with 8 mighty Darlington drivers! This DIP chip contains 8 drivers that can sink 500mA from a 50V supply and has kickback diodes included inside for...

https://www.adafruit.com/product/970
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<td>Gray Tunable Practice Pad with Ambassador Coated Drumhead</td>
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<td>1 x Small Cymbals</td>
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**Hardware List**

Screws, standoffs hex nuts and locknuts used to assemble and fasten parts.

**Mallet Assembly (Single Set)**

- 12x M3x6mm screws
- 4x M3x10mm standoffs
- 2x M3x16mm screws
- 3x M3 locknuts
- 1x M3x14mm screw
Kick Drum Assembly

- 1x 2020 Aluminum Extrusion – 305mm long
- 4x M4x8mm screws
- 4x M4 slim t-nuts
- 2x M3x10mm screws
- 2x M3 hex nuts
- 4x M3x6mm screws
- 4x M5x30mm screws
- 6x M5 hex nuts

Cymbal Assembly

- 1/4-20 D-ring tripod screw
- 3/8 to 1/4 screw adapter
- 2x M5x10mm screw
- 2x M5 hex nuts

Circuit Diagram

The diagram below provides a visual reference for wiring of the components. This diagram was created using the software package Fritzing.

Adafruit Library for Fritzing

Use Adafruit's Fritzing parts library to create circuit diagrams for your projects. Download the library or just grab individual parts. Get the library and parts from GitHub - Adafruit Fritzing Parts.
Wired Connections

Feather M4 Express

- D5 from Feather to Pin #5 on ULN2803A
- D6 from Feather to Pin #6 on ULN2803A
- D9 from Feather to Pin #7 on ULN2803A
- D10 from Feather to Pin #8 on ULN2803A
- 3V from Feather to VCC (upper) rails on Perma-Proto
- GND from Feather to Ground (upper) rails on Perma-Proto

Switch

- EN from Feather to Switch
- GND from Feather to Switch

DC Jack

- Ground to Ground (lower) rails on Perma-Proto
- VCC to VCC (lower) rails on Perma-Proto

ULN2803A

- Pin #10 (VCC) from ULN2803A to VCC (lower) on Perma-Proto
• Pin #9 (GND) from ULN2803A to GND (lower) rails on Perma-Proto

Powering

The Adafruit board can be powered via USB or JST using a 3.7v lipo battery. In this project, a 400mAh lipo battery is used. The lipo battery is rechargeable via the USB port on the board. The switch is wired to the enable and ground pins on the board.

12V Power

The 12V 5A power supply is plugged into the DC jack on the lower power and ground rails on the Perma-Proto.

The power and ground rails connected to the 12V 5A power supply must only be used to power the solenoids NOT the Feather!
3D Printing

Parts List
STL files for 3D printing are oriented to print "as-is" on FDM style machines. Parts are designed to 3D print without any support material. Original design source may be downloaded using the links below.

File names & Quantity
1x snare-noid-mount.stl
2x snare-extrusion-mount.stl
2x snare-extrusion-bracket.stl
3x mallet-stick.stl
3x mallet-noid-plate.stl
3x mallet-noid-linkage.stl
3x mallet-noid-holder.stl
3x mallet-noid-bottom-base.stl
6x mallet-ball.stl
1x feather-case-top-cover.stl
1x feather-case-frame.stl
1x feather-case-bottom-cover.stl

Download CAD files from PrusaPrinters
Download CAD files from Thingiverse
**Mallet Assembly**
The solenoid is inserted into the holder. The solenoid holder is attached to the standoffs on the base with M3x6mm screws. The linkage connector is pinned to the solenoids plunger with an M3x16mm screw and locknut. The linkage mounting plate is secured to the solenoid holder with M3x6mm screws. The linkage is then secured to the mounting plate with an M3x16mm screw and locknut. M3x10mm long standoffs are secured to the base for elevation.

**Kick Drum Assembly**
The solenoid is secured to the mounting plate. Two mounting brackets are secured to the slotted holes on the mounting plate. The brackets slide onto the profile of the 2020 extrusion and secured with M4x8mm screws and slim t-nuts. The base mount is secured to the 2020 extrusion with an M4x8mm long screw and slim t-nut.

**Motion Linkage**
This selection analysis shows the linear motion of the plunger pushing the linkage bar and pivoting at the joint to make the mallet strike. This was created in Fusion 360 using joints and contact sets. Revolute joint type is used in the pivoting point in the linkage bar. Slider joint type is used in the plunger of the solenoid. Contact sets are created between the linkage bar and M3 screw secured to the plunger.
Slicing Parts
No supports are required. Slice with settings for PLA material.

The parts were sliced using CURA using the slice settings below.

PLA filament 220c extruder
0.2 layer height
10% gyroid infill
90mm/s print speed
60c heated bed

Design Source Files
The project assembly was designed in Fusion 360. This can be downloaded in different formats like STEP, STL and more. Electronic components like Adafruit's board, displays, connectors and more can be downloaded from the Adafruit CAD parts GitHub Repo.

CircuitPython on Feather M4 Express

CircuitPython is a derivative of MicroPython designed to simplify experimentation and education on low-cost microcontrollers. It makes it easier than ever to get prototyping by requiring no upfront desktop software downloads. Simply copy and edit files on the CIRCUITPY drive to iterate.

The following instructions will show you how to install CircuitPython. If you've already installed CircuitPython but are looking to update it or reinstall it, the same steps work for that as well!

Set up CircuitPython Quick Start!

Follow this quick step-by-step for super-fast Python power :)
Download the latest version of CircuitPython for this board via CircuitPython.org

Click the link above and download the latest UF2 file.

Download and save it to your desktop (or wherever is handy).

Plug your Feather M4 into your computer using a known-good USB cable.

A lot of people end up using charge-only USB cables and it is very frustrating! So make sure you have a USB cable you know is good for data sync.

Double-click the Reset button next to the USB connector on your board, and you will see the NeoPixel RGB LED turn green. If it turns red, check the USB cable, try another USB port, etc. Note: The little red LED next to the USB connector will pulse red. That's ok!

If double-clicking doesn't work the first time, try again. Sometimes it can take a few tries to get the rhythm right!
You will see a new disk drive appear called FEATHERBOOT.

Drag the adafruit_circuitpython_etc.uf2 file to FEATHERBOOT.

The LED will flash. Then, the FEATHERBOOT drive will disappear and a new disk drive called CIRCUITPY will appear.

That's it, you're done! :)
Thankfully, we can do this in one go. In the example below, click the Download Project Bundle button below to download the necessary libraries and the code.py file in a zip file. Extract the contents of the zip file, open the directory MIDI_Solenoid_Drum_Kit/ and then click on the directory that matches the version of CircuitPython you’re using and copy the contents of that directory to your CIRCUITPY drive.

Your CIRCUITPY drive should now look similar to the following image:

```python
# SPDX-FileCopyrightText: 2020 Liz Clark for Adafruit Industries
# SPDX-License-Identifier: MIT

import time
import board
import digitalio
import usb_midi
import adafruit_midi
from adafruit_midi.note_on import NoteOn

tools = [board.D5, board.D6, board.D9, board.D10]

# array for the solenoids
noids = []

# setup for the solenoid pins to be outputs
for pin in tools:
    noid = digitalio.DigitalInOut(pin)
    noid.direction = digitalio.Direction.OUTPUT
    noids.append(noid)

# MIDI note array
notes = [60, 61, 62, 63]

# MIDI in setup
midi = adafruit_midi.MIDI(midi_in=usb_midi.ports[0], in_channel=0)

# delay for solenoids
speed = 0.03
retract = 0

while True:
    # msg holds MIDI messages
    msg = midi.receive()

    for i in range(4):
        # states for solenoid on/off
        noid_output = noids[i]

        # states for MIDI note recieved
        notes_played = notes[i]

        # if NoteOn msg comes in and the MIDI note # matches with predefined notes:
        if isinstance(msg, NoteOn) and msg.note is notes_played:
            print(time.monotonic(), msg.note)

            # solenoid is triggered
            noid_output.value = True

            # quick delay
            retract = time.monotonic()

            # retracts solenoid using time.monotonic() to avoid delays between notes
```
activating
        if (retract + speed) < time.monotonic():
            noid_output.value = False

Your Feather M4 Express CIRCUITPY drive should look like this after you've copied everything over:

CircuitPython Code Walkthrough

Importing the Libraries

The code begins by importing the CircuitPython libraries.

```python
import time
import board
import digitalio
import usb_midi
import adafruit_midi
from adafruit_midi.note_on import NoteOn
```

Digital Output Pins

Next, the Feather's digital pins are setup to be outputs to send on and off signals to the ULN2803, which will activate the solenoids.

```python
# pins for the solenoid output signals
noid_pins = [board.D5, board.D6, board.D9, board.D10]

# array for the solenoids
noids = []

# setup for the solenoid pins to be outputs
for pin in noid_pins:
    noid = digitalio.DigitalInOut(pin)
    noid.direction = digitalio.Direction.OUTPUT
    noids.append(noid)
```
MIDI Setup

The MIDI notes are setup next. If you need to change the MIDI notes that will activate the solenoids, you can edit this array with the note numbers that you need.

The MIDI object is setup after the notes. The Feather is setup to be a MIDI-in device, meaning that it is receiving MIDI data.

```python
# MIDI note array
notes = [60, 61, 62, 63]

# MIDI in setup
midi = adafruit_midi.MIDI(midi_in=usb_midi.ports[0], in_channel=0)
```

Time Keeping

Finally, two variables are setup. `speed` will act as a delay for how long the solenoids will remain activated before retracting. `retract` will be a `time.monotonic()` device.

```python
# delay for solenoids
speed = 0.03
retract = 0
```

The Loop

The loop begins by setting up `msg` to receive any incoming MIDI data.

```python
while True:
    # msg holds MIDI messages
    msg = midi.receive()
```

Solenoid and MIDI Note Array Indexes

Next, the solenoids' array index position is setup the be held in `noid_output`. The same is done for the MIDI note numbers with `notes_played`.

```python
for i in range(4):
    # states for solenoid on/off
    noid_output = noids[i]

    # states for MIDI note recieved
    notes_played = notes[i]
```
Play the Drum!

Then the real action of the code takes place. If a NoteOn MIDI message is received that matches one of the MIDI note numbers listed in notes_played, then the matching solenoids are activated. retract is also updated to hold the current value of time.monotonic().

```python
# if NoteOn msg comes in and the MIDI note # matches with predefined notes:
if isinstance(msg, NoteOn) and msg.note in notes_played:
    print(time.monotonic(), msg.note)
    # solenoid is triggered
    noid_output.value = True
    # quick delay
    retract = time.monotonic()
```

Finally, the solenoids retract when the sum of retract and speed (0.03) is less than the current time.monotonic() value.

By doing this, you can activate your solenoids at the same time to stay on beat. If you used the more traditional time.sleep(value) to delay the solenoids' retractions, you would run into delays in getting the solenoids to hit the drums.

```python
# retracts solenoid using time.monotonic() to avoid delays between notes activating
if (retract + speed) < time.monotonic():
    noid_output.value = False
```

Feather Header Setup

Feather Headers
The Feather M4 Express and ULN2803A will be fitted onto a halfsize perma-proto PCB. In order to make them removable, the Feather will use female headers. The ULN2803A will snap onto a DIP socket.
Install Headers to Feather
A 12-pin and 16-pin strip of male headers are soldered to the pins on the Feather M4 Express.

Breadboard Helper
A breadboard can help assist by keeping the header pins in place while soldering.

Female Headers for Perma-Proto
Female headers are fitted onto male headers on the Feather M4 Express then fitted onto the Perma-Proto half size PCB. Note the placement of the Feather shows the USB port close to the edge.

Mounting tack can be used to temporarily secure the female headers to the Perma-Proto PCB.
Solder Perma-Proto
Apply solder to all of the pins on the bottom of the Perma-Proto PCB. A panavise can help assist by holding the PCB in place while soldering.

Check Feather Headers
Carefully remove the Feather M4 Express by slowly pulling it out from the female headers. Check to ensure all of the pins have solid solder joints.

ULN2803A Setup

DIP Socket
The ULN2803A will snap onto an 18 pin DIP socket. This allows the IC to be removable if it ever needs to be replaced.
Installing Dip Socket
The DIP socket is placed onto the Perma-Proto half size PCB. Reference the photo for best placement. Use pieces of mounting tack to temporarily secure the socket to the PCB.

Solder Socket to Perma-Proto
Apply solder to all 18 pins from the bottom the Perma-Proto.

Double Check
Check to ensure all of the pins are properly soldered and have solid solder joints.
Solder Connections to Perma-Proto
Reference the circuit diagram for the wired connections. 10-wire silicone cover stranded core ribbon cable is used to keep connections bundled together.

JST–PH Cables
Various JST-PH cables are used for the 4x solenoid DC jacks, toggle switch and 12V DC jack power input. Pieces of heat shrink tubing is used to insulate exposed wire connections.

Cable Lengths
The length of wire is relatively short in order to fit the enclosure. Male JST-PH cables are used for the solenoids. Female JST-PH cables are used for the 12V DC power input and the toggle switch.
DC Jacks and Switches

Solenoid DC Jacks
Four DC jacks are used to connect the solenoids. These will be panel mounted to the enclosure. JST-PH female cables are soldered to each DC jack. The cables are approximately 30mm in length (1.2in).

DC Jack Polarity
Reference the photo for the correct polarity. The terminal with the large contact is VCC / voltage. The middle pin is not used. The remaining pin is ground.

Wire Switch and DC Jack
The toggle switch and 12VDC jack are wired to male JST-PH cables. These are also about 30mm in length (1.2in).
Solenoid Wiring

Wire Solenoids
The 12V solenoids come with long pre-tinned wires. These will be soldered to a cable with a 2.1mm barrel plug. This makes it easy to plug it into the DC jacks.

Solder Wires
Using wire strippers, remove a bit of insulation for each wire. Tin the wires by adding a bit of solder. This helps prevent the strands of wire from fraying. Solder the wires from the solenoid to the cable with the 2.1mm barrel plug. The wire with the lined dashes is the VCC / voltage wire. Use pieces of heat shrink tubing to insulation the exposed connections.

Soldered 2.1mm Barrel Cable
Check the cabling is properly soldered and has a solid connections. Repeat this process for the other solenoids.
Case Assembly

Install Perma-Proto to Covers
The wired Perma-Proto snap fits onto the bottom cover of the enclosure. Place the PCB over the standoffs and fit edge of the PCB under one of the tabs on the side. Press down to snap fit onto other tab. Adjust wires so the cables are not being kinked or pinched.

Panel Mount DC Jacks
Install the four DC jacks into the case by fitting them through the holes on the side of the enclosure frame.

Panel Mount Switch and DC Jack
Insert the hex nuts onto the DC jacks and tightly fasten. Proceed to panel mount the toggle switch and the 12VDC jack for power input.
Connect Switch and DC Jack
Plug in the toggle switch to the JST-PH connect that is connected to the EN and GND pins on the Feather. Plug in the 12VDC power input to the JST-PH connector that is wired to the power and ground rails on the Perma-Proto PCB.

Connect DC Jacks for Solenoids
Plug in the DC jacks for the solenoids to the various JST-PH connectors on the Perma-Proto PCB.

Install Case to Cover
Fit the enclosure frame over the bottom cover with the notch lined up with the USB port on the Feather. Check to ensure all of the wires are fitted inside the case. Firmly press to snap fit together.

Install Top Cover
Place the top cover over the enclosure frame. Check to ensure all of the wires are fitted inside the case. Firmly press to snap fit close.
Mallet Assembly

Solenoid Holder
The solenoids are fitted into these holders and secured with M3 screws.

Install Solenoid
Install the solenoid into a holder by sliding it in with the piston fitting through the center hole. The mounting holes should be lined up with the holes on the side of the holder.

Install Linkage Plate
Place the plate over the solenoid holder with the mounting holes lined up.
Secure Plate to Holder
Insert and fasten 4x M3 x 6mm long screws to secure the plate to the solenoid holder.

Hardware for Base
M3 standoffs are used to elevate the solenoid. Taller standoffs allow for more height clearance. Choose the length of standoff you'll want to use for your setup. In this project, 10mm long M3 standoffs are used.

Install Standoffs
Use M3 screws to install four M3 standoffs to the slots on the side of the base.
Secure Standoffs
Tightly fasten M3 screws to the standoffs.

Install Solenoid Holder to Base
Place the solenoid holder over the standoffs on the base. Line up the slot with the M3 standoffs.

Secure Solenoid Holder to Base
Install and fasten M3 screws over the slots on the solenoid holder.
Mallet Hardware
Super glue the two dome halves to make the head of the mallet. Glue the head to the mallet stick. The mallet is secured to the linkage using an M3 x 16mm long screw and lock nut (with nylon insert).

Secure Mallet Parts
Place the mallet stick over the linkage with the mounting holes line up. Reference the photo for best placement. Insert the M3 x 16mm long screws through both mallet stick and linkage. Insert and tightly fasten the M3 locknut.

Assembled Mallet and Linkage
Inspect the mallet and linkage to ensure installation is correct.
Installing Mallet to Solenoid Plate
The assembled mallet and linkage will be secured to the linkage plate on the solenoid holder using an M3 x 16mm long screw and locknut.

Install Linkage to Solenoid
Fit the linkage through the slit on the end of the solenoid with the large spring. Line up the mounting holes.

Secure Linkage
Insert the M3 x 16mm long screw through the mounting holes. The screw will go through both the solenoid and linkage. Install and tightly fasten the M3 locknut onto the thread of the screw.
Install Linkage to Plate
Line up the center hole on the linkage with the mounting holes on the linkage plate.

Secure Linkage to Plate
Insert the M3 x 16mm long screw through the holes in both the linkage plate and the linkage. Insert and tightly fasten the M3 locknut onto the thread of the screw.

Test Motion
Press the piston on the solenoid down to test out the mallet. It should actuate the mallet down and spring back when released. Loosen the locknut if the motion is too tight from the friction.
Degree of Rotation
The 12V solenoid features a push / pull of 10mm throw. The mallet has about 18º degrees of rotation.

Assembled Solenoid Mallet
Proceed to repeat this process for more solenoids. In this project, we created three sets of solenoid mallets.

2020 Assembly

Solenoid Mounting Parts
Get the parts and hardware ready for the mounting the solenoid to a piece of 2020 aluminum extrusion.

2x M4 Slim t-nuts
2x M4 x 8mm long screws
2x M3 x 10mm long screws
2x M3 hex nuts
Install Slim T-Nuts to Brackets
Insert the two M4 x 8mm long screws through the mounting holes on the two brackets. Insert and fasten the M4 slim t-nuts onto the threads of the screws. This will make fitting onto the 2020 extrusion easier later in the assembly.

Secure Brackets to Mounting Plate
Place the brackets onto the slotted holes on the mounting plate. Reference the photo for correct placement.

Installing Mounting Plate to Solenoid
The mounting plate is secured to the solenoid using four M3 x 6mm long machine screws.
Install Mounting Plate
Place the assembled mounting plate over the solenoid and line up the mounting holes. Reference the image for correct orientation.

Secure Mounting Plate to Solenoid
Insert and fasten four M3 x 6mm long screws to secure the mounting plate to the solenoid.

Assembled Solenoid Mount
The solenoid mount is ready to fit onto a piece of 2020 aluminum extrusion. Check to ensure the slim t-nuts are preinstalled onto the brackets.
Hardware for 2020 Base
Get the hardware ready for assembling the base for the 2020 extrusion.

- 2x M5 x 30mm long screws
- 6x M5 hex nuts
- 1x M4 x 8mm long screw
- 1x M4 slim t-nut

Setup Legs for 2020 Base
Insert the two M5 x 30mm long screws into the base feet. Insert two M5 hex nuts onto the threads of each screw. Reference the photo for best placement. These rubber bumper feet are stuck on the bottom for better grip.

Install T-Nuts onto 2020 Base
Insert the M4 x 8mm long screw through the hole on the 2020 base. Install and fasten the M4 slim t-nut onto the thread of the screw. This will make it easier to fit onto the 2020 extrusion.
Install Hex Nuts to 2020 Base
Press fit two of the M5 hex nuts onto the recessed holes on the 2020 base.

Install Legs to 2020 Base
Fasten the legs onto the M5 hex nuts that were fitted into the 2020 base. Reference photo for best placement.

Tighten Hex Nuts
Use a wrench or vise grips too tightly fasten the hex nuts. The height of the 2020 mount can be adjusted by twisting the thread to a desired length.
Pair of 2020 Base Mounts
Proceed to create a second 2020 base mount. One will go on each side of 2020 aluminum extrusion.

Install Solenoid Mount to 2020 Extrusion
Fit the brackets from the solenoid to the slots on the 2020 aluminum extrusion. Ensure the slim t-nut is properly fitted through the slots.

Solenoid Wiring
The solenoid cable is fitted through the brackets before installing onto the piece of 2020 aluminum extrusion. This helps keep the wiring hidden inside the slots of the extrusion.
Height Adjustment
The solenoid can be adjusted by loosening the two M3 screws that secure the solenoid holder to the brackets. The slotted holes allow for height adjustments.

Secure 2020 Mounting Brackets
The brackets are able to slide along the 2020 aluminum extrusion. Tighten the two M4 screws on the brackets to secure the solenoid in place.

Installing DC Cable
The 2.1mm barrel connector is fitted through the 2020 base. This allows the cable to be routed outside of the extrusion.
Install Base Mount
Fit the base mount over the end of the 2020 aluminum extrusion. Carefully fit the slim t-nut into the slot. Ensure the cable from the solenoid is not being kinked or pinched.

Assembled 2020 Solenoid
Double check all of the screws are nice and tight. The height of the solenoid and legs can be adjusted to fit over a snare drum or practice pad.

Usage

Setup DAW Software Instruments
The Feather M4 Express will show up as a USB MIDI device when connected to a computer. MIDI software instrument with capabilities to create external MIDI out instruments will need to be setup in order to get the solenoids to fire.

This project was tested with Logic Pro X on Mac OS. Follow the instructions below to get setup.
Mac OS – Audio MIDI Setup
The Feather M4 Express will should up in the MIDI studio window in the Audio MIDI setup application. Right-click Edit device to open the properties window. There you can change the device name and ports. Nothing needs to be changes here, just FYI.

Logic Pro X – External MIDI Track
In the track list, right-click and choose "New External MIDI Track". This allow you to assign the Feather M4 Express to a MIDI track. Using a MIDI track allows you can create musical MIDI notes.

MIDI Track Port
In the Inspector panel, under the Track section, select Feather M4 Express from the Port dropdown. This will assign any MIDI notes in the track to the Feather M4 Express.
Keyboard Playing
MIDI notes can be played live using your computer's keyboard. In the top menu, select Window > Show Keyboard. Use the interface to trigger music notes, change octaves, velocity, etc. This is a great way to test solenoids and play live.

Create MIDI Notes
In the timeline, right-click and select Create MIDI Region. Write your MIDI notes in the piano roll using the pencil tool. Use the notes that are programmed in CircuitPython code.py file.

C4 60, C#4 61, D4 62, D#4 63