Adafruit AirLift FeatherWing - ESP32 WiFi Co-Processor
Created by Brent Rubell


Last updated on 2021-11-15 07:41:14 PM EST
# Table of Contents

<table>
<thead>
<tr>
<th>Section</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Overview</td>
<td>5</td>
</tr>
<tr>
<td>Pinouts</td>
<td></td>
</tr>
<tr>
<td>• Power Pins</td>
<td>7</td>
</tr>
<tr>
<td>• SPI and Control Pins</td>
<td>8</td>
</tr>
<tr>
<td>• RGB LED</td>
<td>9</td>
</tr>
<tr>
<td>Assembly</td>
<td>10</td>
</tr>
<tr>
<td>• Prepare the header strip:</td>
<td>10</td>
</tr>
<tr>
<td>• Add the FeatherWing:</td>
<td>10</td>
</tr>
<tr>
<td>• And Solder!</td>
<td>11</td>
</tr>
<tr>
<td>CircuitPython WiFi</td>
<td>13</td>
</tr>
<tr>
<td>• CircuitPython Microcontroller Pinout</td>
<td>13</td>
</tr>
<tr>
<td>• CircuitPython Installation of ESP32SPI Library</td>
<td>14</td>
</tr>
<tr>
<td>• CircuitPython Usage</td>
<td>14</td>
</tr>
<tr>
<td>Internet Connect!</td>
<td>16</td>
</tr>
<tr>
<td>• What's a secrets file?</td>
<td>16</td>
</tr>
<tr>
<td>• Connect to WiFi</td>
<td>17</td>
</tr>
<tr>
<td>• Requests</td>
<td>21</td>
</tr>
<tr>
<td>• HTTP GET with Requests</td>
<td>23</td>
</tr>
<tr>
<td>• HTTP POST with Requests</td>
<td>24</td>
</tr>
<tr>
<td>• Advanced Requests Usage</td>
<td>25</td>
</tr>
<tr>
<td>• WiFi Manager</td>
<td>26</td>
</tr>
<tr>
<td>CircuitPython BLE</td>
<td>29</td>
</tr>
<tr>
<td>• CircuitPython BLE UART Example</td>
<td>29</td>
</tr>
<tr>
<td>• Update the AirLift Firmware</td>
<td>30</td>
</tr>
<tr>
<td>• Install CircuitPython Libraries</td>
<td>30</td>
</tr>
<tr>
<td>• Install the Adafruit Bluefruit LE Connect App</td>
<td>31</td>
</tr>
<tr>
<td>• Copy and Adjust the Example Program</td>
<td>31</td>
</tr>
<tr>
<td>• Talk to the AirLift via the Bluefruit LE Connect App</td>
<td>32</td>
</tr>
<tr>
<td>Arduino WiFi</td>
<td>35</td>
</tr>
<tr>
<td>• Arduino Microcontroller Pin Definitions</td>
<td>35</td>
</tr>
<tr>
<td>• Feather NRF52832</td>
<td>36</td>
</tr>
<tr>
<td>• Teensy</td>
<td>36</td>
</tr>
<tr>
<td>• Library Install</td>
<td>37</td>
</tr>
<tr>
<td>• First Test</td>
<td>38</td>
</tr>
<tr>
<td>• WiFi Connection Test</td>
<td>39</td>
</tr>
<tr>
<td>• Secure Connection Example</td>
<td>41</td>
</tr>
<tr>
<td>• JSON Parsing Demo</td>
<td>44</td>
</tr>
<tr>
<td>• Adapting Other Examples</td>
<td>45</td>
</tr>
<tr>
<td>Upgrade External ESP32 Airlift Firmware</td>
<td>45</td>
</tr>
<tr>
<td>• External AirLift FeatherWing, Shield, or ItsyWing</td>
<td>45</td>
</tr>
<tr>
<td>• Upload Serial Passthrough code for Feather or ItsyBitsy</td>
<td>46</td>
</tr>
<tr>
<td>• External AirLift Breakout</td>
<td>48</td>
</tr>
<tr>
<td>• Code Usage</td>
<td>50</td>
</tr>
<tr>
<td>• Install esptool.py</td>
<td>51</td>
</tr>
</tbody>
</table>
• Burning nina-fw with esptool
• Verifying the Upgraded Firmware Version
• Arduino
• CircuitPython

Downloads
• Files
• Schematic
• Fab Print
Give your Feather project a lift with the Adafruit AirLift FeatherWing - a FeatherWing that lets you use the powerful ESP32 as a WiFi or BLE co-processor. You probably have your favorite Feather (like the Feather M4 (https://adafru.it/Cmy)) that comes with its own set of awesome peripherals and lots of libraries. But it doesn't have WiFi built in! So let's give that chip a best friend, the ESP32. This chip can handle all the heavy lifting of connecting to a WiFi network and transferring data from a site, even if it's using the latest TLS/SSL encryption (it has root certificates pre-burned in).

Having WiFi managed by a separate chip means your code is simpler, you don't have to cache socket data, or compile in & debug an SSL library. Send basic but powerful socket-based commands over 8MHz SPI for high speed data transfer. You can use 3V or 5V Arduino, any chip from the ATmega328 or up, although the '328 will not be able to do very complex tasks or buffer a lot of data. It also works great with CircuitPython, a SAMD51/Cortex M4 minimum required since we need a bunch of RAM. All you need is an SPI bus and 2 control pins plus a power supply that can provide up to 250mA during WiFi usage.

The ESP32 also supports BLE (Bluetooth Low Energy), though not simultaneously with WiFi. Many of our CircuitPython builds include native support for ESP32 BLE. You use a few control pins and the RXI and TXO pins to talk to the ESP32 when it's in BLE mode.
We placed an ESP32 module on a FeatherWing with a separate 3.3V regulator, and a tri-state chip for MOSI so you can share the SPI bus with other 'Wing. Comes fully assembled and tested, pre-programmed with ESP32 SPI WiFi co-processor firmware that you can use in CircuitPython to use this into WiFi co-processor over SPI + 2 pins (https://adafruit.it/Evl). We also toss in some header so you can solder it in and plug into a doubler, but you can also pick up a set of stacking headers to stack above /below your Feather.

We've tested this with all our Feathers and it should work just fine with them except the ESP8266 & ESP32 Feathers (cause they already have WiFi). For use in Arduino, the '328 and '32u4 you can do basic connectivity and data transfer but they do not have a lot of RAM so we don't recommend them - use the M0, M4 or similar, for best results! For CircuitPython use, a Feather M4 or nRF52840 works best - the M0 series does not have enough RAM in CircuitPython.

The firmware on board is a slight variant of the Arduino WiFiNINA core, which works great! (https://adafruit.it/E7O)
Pinouts

Power Pins

- GND - Common power/logic ground.
- BAT - Positive voltage from JST on Feather for an optional LiPo battery.
- USB - Positive voltage to/from the Micro USB jack if connected.
- EN - 3.3V regulator's enable pin. It's pulled up, so connect to ground to disable the 3.3V regulator.
- 3V - this is the output from the 3.3V regulator. The regulator can supply 500mA peak but half of that is drawn by the ESP32, and it's a fairly power-hungry chip. So if you need a ton of power for stuff like LEDs, motors, etc. Use the USB or BAT pins, and an additional regulator.
SPI and Control Pins

To keep transfers speedy, we use SPI not UART Serial. UART is too slow and hard to synchronize. This uses more pins but the experience is much better!

Classic SPI Pins:

- **SCK** - SPI Clock from your microcontroller, level shifted so can be 3-5V logic
- **MISO** - SPI Data from the AirLift to the microcontroller, this is 3.3V logic out, can be read by 3-5V logic. This is tri-stated when not selected, so you can share the SPI bus with other devices.
- **MOSI** - SPI Data to the AirLift from the microcontroller, level shifted so can be 3-5V logic
- **ESPCS** - SPI Chip Select from the microcontroller to start sending commands to the AirLift, level shifted so can be 3-5V logic
Required Control Pins:

- **ESPBUSY** - this pin is an input from the AirLift, it will let us know when its ready for more commands to be sent. This is 3.3V logic out, can be read by 3-5V logic. This pin must be connected.
- **ESPRST** - this pin is an output to the AirLift. Set low to put the AirLift into reset. You should use this pin, even though you might be able to run for a short while without it, it's essential to 'kick' the chip if it ever gets into a locked up state. Level shifted so can be 3-5V logic

Optional Control Pins:

- **ESPGPIO0** - this is the ESP32 GPIO0 pin, which is used to put it into bootloading mode. It is also used if you like when the ESP32 is acting as a server, to let you know data is ready for reading. It's not required for WiFi, but you'll need to connect it to use BLE mode. Solder the pad on the bottom of the FeatherWing to connect it.
- **ESPRX & ESPTX** - Serial data in and Serial data out, used for bootloading new firmware, and for communication when in BLE mode. Leave disconnected if not using BLE or when not uploading new WiFi firmware to the AirLift (which is a rare occurrence). You'll need to solder the two pads on the bottom of the FeatherWing to use these pins.

**RGB LED**

There is a small RGB LED to the left of the ESP32. These RGB LEDs are available in the Arduino and CircuitPython libraries if you'd like to PWM them for a visual alert. They're connected to the ESP32's pins 26 (Red), 25 (Green), and 27 (Blue).
Assembly

Prepare the header strip:

Cut the strip to length if necessary. It will be easier to solder if you insert it into a breadboard - long pins down

Add the FeatherWing:

Place the FeatherWing over the pins so that the short pins poke through the two rows of breakout pads
And Solder!
Be sure to solder all pins for reliable electrical contact.

(For tips on soldering, be sure to check out our Guide to Excellent Soldering (https://adafruit.it/aTk)).

Start by soldering the first row of headers
Now flip around and solder the other row completely
You're done!

CircuitPython WiFi

It's easy to use the Adafruit AirLift breakout with CircuitPython and the Adafruit CircuitPython ESP32SPI (https://adafruit.it/DWV) module. This module allows you to easily add WiFi to your project.

The ESP32SPI library requires a microcontroller with ~128KB of RAM or more. The SAMD21 will not work.

CircuitPython Microcontroller Pinout

Since all CircuitPython-running Feathers follow the same pinout, you do not need to change any of the pins listed below.

To use the ESP32’s pins, copy the following lines into your code:

```python
esp32_cs = DigitalInOut(board.D13)
esp32_ready = DigitalInOut(board.D11)
esp32_reset = DigitalInOut(board.D12)
```

If you wish to use the ESP32’s GPIO0 pin - solder the jumper on the back of the FeatherWing, highlighted in red.
Then, include the following code to use the pin:

```python
esp32_gpio0 = DigitalInOut(board.D10)
```

## CircuitPython Installation of ESP32SPI Library

You'll need to install the [Adafruit CircuitPython ESP32SPI](https://adafruit.it/DWV) library on your CircuitPython board.

First make sure you are running the latest version of Adafruit CircuitPython [https://adafruit.it/Amd](https://adafruit.it/Amd) for your board.

Next you'll need to install the necessary libraries to use the hardware--carefully follow the steps to find and install these libraries from Adafruit's CircuitPython library bundle [https://adafruit.it/uap](https://adafruit.it/uap). Our CircuitPython starter guide has a great page on how to install the library bundle [https://adafruit.it/ABU](https://adafruit.it/ABU).

You can manually install the necessary libraries from the bundle:

- adafruit_esp32spi
- adafruit_requests.mpy
- adafruit_bus_device

Before continuing make sure your board's lib folder or root filesystem has the adafruit_esp32spi, adafruit_requests.mpy, and adafruit_bus_device files and folders copied over.

Next make sure you are set up to connect to the serial console [https://adafruit.it/Bec](https://adafruit.it/Bec)

## CircuitPython Usage

Copy the following code to your code.py file on your microcontroller:

```python
import board
import busio
from digitalio import DigitalInOut

from adafruit_esp32spi import adafruit_esp32spi

print("ESP32 SPI hardware test")
```
```python
esp32_cs = DigitalInOut(board.D13)
esp32_ready = DigitalInOut(board.D11)
esp32_reset = DigitalInOut(board.D12)

spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
esp = adafruit_esp32spi.ESP_SPIcontrol(spi, esp32_cs, esp32_ready, esp32_reset)

if esp.status == adafruit_esp32spi.WL_IDLE_STATUS:
    print("ESP32 found and in idle mode")
    print("Firmware vers.", esp.firmware_version)
    print("MAC addr:", [hex(i) for i in esp.MAC_address])

    for ap in esp.scan_networks():
        print("%s		RSSI: %d" % (str(ap['ssid']), 'utf-8'), ap['rssi']))

    print("Done!")
```

Connect to the serial console (https://adafruit.it/BIO) to see the output. It should look something like the following:

![Code output](image)

Make sure you see the same output! If you don't, check your wiring. Note that we've changed the pinout in the code example above to reflect the CircuitPython Microcontroller Pinout at the top of this page.

Once you've succeeded, continue onto the next page!

If you can read the Firmware and MAC address but fails on scanning SSIDs, check your power supply, you may be running out of juice to the ESP32 and it's resetting.
Internet Connect!

Once you have CircuitPython setup and libraries installed we can get your board connected to the Internet.

To get connected, you will need to start by creating a secrets file.

What's a secrets file?

We expect people to share tons of projects as they build CircuitPython WiFi widgets. What we want to avoid is people accidentally sharing their passwords or secret tokens and API keys. So, we designed all our examples to use a `secrets.py` file, that is in your CIRCUITPY drive, to hold secret/private/custom data. That way you can share your main project without worrying about accidentally sharing private stuff.

Your secrets.py file should look like this:

```python
# This file is where you keep secret settings, passwords, and tokens!
# If you put them in the code you risk committing that info or sharing it

secrets = {
    'ssid' : 'home ssid',
    'password' : 'my password',
    'timezone' : "America/New_York", # http://worldtimeapi.org/timezones
    'github_token' : 'fawfj23rakjnfwiefja',
    'hackaday_token' : 'h4xx0rs3kret',
}
```

Inside is a python dictionary named secrets with a line for each entry. Each entry has an entry name (say 'ssid') and then a colon to separate it from the entry key 'home ssid' and finally a comma ,

At a minimum you'll need the ssid and password for your local WiFi setup. As you make projects you may need more tokens and keys, just add them one line at a time. See for example other tokens such as one for accessing github or the hackaday API. Other non-secret data like your timezone can also go here, just cause its called secrets doesn't mean you can't have general customization data in there!

For the correct time zone string, look at [http://worldtimeapi.org/timezones](https://adafruit.it/EcP) and remember that if your city is not listed, look for a city in the same time zone, for example Boston, New York, Philadelphia, Washington DC, and Miami are all on the same time as New York.
Of course, don't share your secrets.py - keep that out of GitHub, Discord or other project-sharing sites.

Connect to WiFi

OK now you have your secrets setup - you can connect to the Internet using the ESP32SPI and the Requests modules.

First make sure you are running the latest version of Adafruit CircuitPython (https://adafruit.it/Amd) for your board.

Next you'll need to install the necessary libraries to use the hardware--carefully follow the steps to find and install these libraries from Adafruit's CircuitPython library bundle (https://adafruit.it/zdx). Our introduction guide has a great page on how to install the library bundle (https://adafruit.it/ABU) for both express and non-express boards.

Remember for non-express boards like the Feather M0, you'll need to manually install the necessary libraries from the bundle:

- adafruit_bus_device
- adafruit_esp32_spi
- adafruit_requests
- neopixel

Before continuing make sure your board's lib folder or root filesystem has the above files copied over.

Next connect to the board's serial REPL (https://adafruit.it/Awz) so you are at the CircuitPython >>> prompt.

Into your lib folder. Once that's done, load up the following example using Mu or your favorite editor:

```python
# SPDX-FileCopyrightText: 2019 ladyada for Adafruit Industries
# SPDX-License-Identifier: MIT

import board
import busio
from digitalio import DigitalInOut
import adafruit_requests as requests
import adafruit_espm32spi.adafruit_esp32spi_socket as socket
from adafruit_esp32spi import adafruit_esp32spi

# Get wifi details and more from a secrets.py file
try:
```
from secrets import secrets
except ImportError:
    print("WiFi secrets are kept in secrets.py, please add them there!")
    raise

print("ESP32 SPI webclient test")

TEXT_URL = "http://wifitest.adafruit.com/testwifi/index.html"
JSON_URL = "http://api.coindesk.com/v1/bpi/currentprice/USD.json"

# If you are using a board with pre-defined ESP32 Pins:
esp32_cs = DigitalInOut(board.ESP_CS)
esp32_ready = DigitalInOut(board.ESP_BUSY)
esp32_reset = DigitalInOut(board.ESP_RESET)

# If you have an AirLift Shield:
# esp32_cs = DigitalInOut(board.D10)
# esp32_ready = DigitalInOut(board.D7)
# esp32_reset = DigitalInOut(board.D5)

# If you have an AirLift Featherwing or ItsyBitsy Airlift:
# esp32_cs = DigitalInOut(board.D13)
# esp32_ready = DigitalInOut(board.D11)
# esp32_reset = DigitalInOut(board.D12)

# If you have an externally connected ESP32:
# NOTE: You may need to change the pins to reflect your wiring
# esp32_cs = DigitalInOut(board.D9)
# esp32_ready = DigitalInOut(board.D10)
# esp32_reset = DigitalInOut(board.D5)

spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
esp = adafruit_esp32spi.ESP_SPIcontrol(spi, esp32_cs, esp32_ready, esp32_reset)
requests.set_socket(socket, esp)

if esp.status == adafruit_esp32spi.WL_IDLE_STATUS:
    print("ESP32 found and in idle mode")
print("Firmware vers.", esp.firmware_version)
print("MAC addr:", [hex(i) for i in esp.MAC_address])

for ap in esp.scan_networks():
    print("%ss\t	RSSI: %d" % (str(ap["ssid"], "utf-8"), ap["rssi"]))

print("Connecting to AP...")
while not esp.is_connected:
    try:
        esp.connect_AP(secrets["ssid"], secrets["password"])
    except RuntimeError as e:
        print("could not connect to AP, retrying: ", e)
        continue
print("Connected to", str(esp.ssid, "utf-8"), "\tRSSI:", esp.rssi)
print("My IP address is", esp.pretty_ip(esp.ip_address))
print("IP lookup adafruit.com: %s" % esp.pretty_ip(esp.get_host_by_name("adafruit.com")))
print("Ping google.com: %d ms" % esp.ping("google.com"))

# esp.debug = True

print("Fetching text from", TEXT_URL)
r = requests.get(TEXT_URL)
print("." * 40)
print(r.text)
print("." * 40)
r.close()

print()
```python
print("Fetching json from", JSON_URL)
r = requests.get(JSON_URL)
print("-" * 40)
print(r.json())
print("-" * 40)
r.close()
print("Done!")
```

And save it to your board, with the name `code.py`.

This first connection example doesn't use a secrets file - you'll hand-enter your SSID/password to verify connectivity first!

Then go down to this line

```python
esp.connect_AP(b'MY_SSID_NAME', b'MY_SSID_PASSWORD')
```

and change `MY_SSID_NAME` and `MY_SSID_PASSWORD` to your access point name and password, keeping them within the " quotes. (This example doesn't use the secrets' file, but its also very stand-alone so if other things seem to not work you can always re-load this. You should get something like the following:

In order, the example code...
Initializes the ESP32 over SPI using the SPI port and 3 control pins:

```python
esp32_cs = DigitalInOut(board.ESP_CS)
esp32_ready = DigitalInOut(board.ESP_BUSY)
esp32_reset = DigitalInOut(board.ESP_RESET)
spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
esp = adafruit_esp32spi.ESP_SPIcontrol(spi, esp32_cs, esp32_ready, esp32_reset)
```

To use the AirLift FeatherWing's pins, replace the following lines into your code:

```python
esp32_cs = DigitalInOut(board.D13)
esp32_ready = DigitalInOut(board.D11)
esp32_reset = DigitalInOut(board.D12)
```

Tells our `requests` library the type of socket we're using (socket type varies by connectivity type - we'll be using the `adafruit_esp32spi_socket` for this example). We'll also set the interface to an `esp` object. This is a little bit of a hack, but it lets us use `requests` like CPython does.

```python
requests.set_socket(socket, esp)
```

Verifies an ESP32 is found, checks the firmware and MAC address

```python
if esp.status == adafruit_esp32spi.WL_IDLE_STATUS:
    print("ESP32 found and in idle mode")
    print("Firmware vers.", esp.firmware_version)
    print("MAC addr:", [hex(i) for i in esp.MAC_address])
```

Performs a scan of all access points it can see and prints out the name and signal strength:

```python
for ap in esp.scan_networks():
    print("%s \t RSSI: %d" % (str(ap['ssid'], 'utf-8'), ap['rssi']))
```

Connects to the AP we've defined here, then prints out the local IP address, attempts to do a domain name lookup and ping google.com to check network connectivity (note sometimes the ping fails or takes a while, this isn't a big deal)

```python
print("Connecting to AP...")
esp.connect_AP(b'MY_SSID_NAME', b'MY_SSID_PASSWORD')
print("Connected to", str(esp.ssid, 'utf-8'), "\tRSSI:", esp.rssi)
print("My IP address is", esp.pretty_ip(esp.ip_address))
print("IP lookup adafruit.com: %s" % esp.pretty_ip(esp.get_host_by_name("adafruit.com")))
print("Ping google.com: %d ms" % esp.ping("google.com"))
```
OK now we’re getting to the really interesting part. With a SAMD51 or other large-RAM (well, over 32 KB) device, we can do a lot of neat tricks. Like for example we can implement an interface a lot like requests (https://adafru.it/E9o) - which makes getting data really really easy.

To read in all the text from a web URL call requests.get - you can pass in https URLs for SSL connectivity

```python
TEXT_URL = "http://wifitest.adafruit.com/testwifi/index.html"
print("Fetching text from", TEXT_URL)
r = requests.get(TEXT_URL)
print('-'*40)
print(r.text)
print('-'*40)
r.close()
```

Or, if the data is in structured JSON, you can get the json pre-parsed into a Python dictionary that can be easily queried or traversed. (Again, only for nRF52840, M4 and other high-RAM boards)

```python
JSON_URL = "http://api.coindesk.com/v1/bpi/currentprice/USD.json"
print("Fetching json from", JSON_URL)
r = requests.get(JSON_URL)
print('-'*40)
print(r.json())
print('-'*40)
r.close()
```

Requests

We've written a requests-like (https://adafru.it/FpT) library for web interfacing named Adafruit_CircuitPython_Requests (https://adafru.it/FpW). This library allows you to send HTTP/1.1 requests without "crafting" them and provides helpful methods for parsing the response from the server.

Here's an example of using Requests to perform GET and POST requests to a server.

```python
# SPDX-FileCopyrightText: 2021 ladyada for Adafruit Industries
# SPDX-License-Identifier: MIT

# adafruit_requests usage with an esp32spi_socket
import board
import busio
from digitalio import DigitalInOut
import adafruit_esp32spi.adafruit_esp32spi_socket as socket
import adafruit_requests as requests

# Add a secrets.py to your filesystem that has a dictionary called secrets with "ssid" and
```
# "password" keys with your WiFi credentials. DO NOT share that file or commit it into Git or other
# source control.
# pylint: disable=no-name-in-module,wrong-import-order
try:
    from secrets import secrets
except ImportError:
    print("WiFi secrets are kept in secrets.py, please add them there!")
    raise

# If you are using a board with pre-defined ESP32 Pins:
# esp32_cs = DigitalInOut(board.ESP_CS)
# esp32_ready = DigitalInOut(board.ESP_BUSY)
# esp32_reset = DigitalInOut(board.ESP_RESET)

# If you have an externally connected ESP32:
# esp32_cs = DigitalInOut(board.D9)
# esp32_ready = DigitalInOut(board.D10)
# esp32_reset = DigitalInOut(board.D5)

# If you have an Airlift Featherwing or ItsyBitsy Airlift:
# esp32_cs = DigitalInOut(board.D13)
# esp32_ready = DigitalInOut(board.D11)
# esp32_reset = DigitalInOut(board.D12)

spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
esp = adafruit_esp32spi.ESP_SPIcontrol(spi, esp32_cs, esp32_ready, esp32_reset)

print("Connecting to AP...")
while not esp.is_connected:
    try:
        esp.connect_AP(secrets["ssid"], secrets["password"])
    except RuntimeError as e:
        print("could not connect to AP, retrying: ", e)
        continue
    print("Connected to", str(esp.ssid, "utf-8"), "\RSSI:", esp.rssi)

# Initialize a requests object with a socket and esp32spi interface
socket.set_interface(esp)
requests.set_socket(socket, esp)

TEXT_URL = "http://wifitest.adafruit.com/testwifi/index.html"
JSON_GET_URL = "https://httpbin.org/get"
JSON_POST_URL = "https://httpbin.org/post"

print("Fetching text from %s" % TEXT_URL)
response = requests.get(TEXT_URL)
print("-" * 40)
print("Text Response: ", response.text)
print("-" * 40)
response.close()

print("Fetching JSON data from %s" % JSON_GET_URL)
response = requests.get(JSON_GET_URL)
print("-" * 40)
print("JSON Response: ", response.json())
print("-" * 40)
response.close()
data = "31F"
print("POSTing data to {0}: {1}".format(JSON_POST_URL, data))
response = requests.post(JSON_POST_URL, data=data)
print("-" * 40)

json.resp = response.json()
# Parse out the 'data' key from json.resp dict.
print("Data received from server: ", json.resp["data"]

©Adafruit Industries
The code first sets up the ESP32SPI interface. Then, it initializes a `requests` object using an ESP32 `socket` and the `esp` object.

```python
import board
import busio
from digitalio import DigitalInOut
import adafruit_esp32spi.adafruit_esp32spi_socket as socket
from adafruit_esp32spi import adafruit_esp32spi
import adafruit_requests as requests

# If you have an externally connected ESP32:
esp32_cs = DigitalInOut(board.D9)
esp32_ready = DigitalInOut(board.D10)
esp32_reset = DigitalInOut(board.D5)
spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
esp = adafruit_esp32spi.ESP_SPIcontrol(spi, esp32_cs, esp32_ready, esp32_reset)

print("Connecting to AP...")
while not esp.is_connected:
    try:
        esp.connect_AP(b'MY_SSID_NAME', b'MY_SSID_PASSWORD')
    except RuntimeError as e:
        print("could not connect to AP, retrying: ", e)
        continue
    print("Connected to", str(esp.ssid, 'utf-8'), "\tRSSI:", esp.rssi)

# Initialize a requests object with a socket and esp32spi interface
requests.set_socket(socket, esp)
```

Make sure to set the ESP32 pinout to match your AirLift breakout's connection:

```python
esp32_cs = DigitalInOut(board.D9)
esp32_ready = DigitalInOut(board.D10)
esp32_reset = DigitalInOut(board.D5)
```

HTTP GET with Requests

The code makes a HTTP GET request to Adafruit's WiFi testing website - http://wifitest.adafruit.com/testwifi/index.html (https://adafruit.it/Fp-).
To do this, we’ll pass the URL into `requests.get()`. We’re also going to save the response from the server into a variable named `response`.

While we requested data from the server, we’d what the server responded with. Since we already saved the server’s `response`, we can read it back. Luckily for us, request’s automatically decodes the server’s response into human-readable text, you can read it back by calling `response.text`.

Lastly, we’ll perform a bit of cleanup by calling `response.close()`. This closes, deletes, and collect’s the response's data.

```python
print("Fetching text from %s"%TEXT_URL)
response = requests.get(TEXT_URL)
print('.'*40)
print("Text Response: ", response.text)
print('.'*40)
response.close()
```

While some servers respond with text, some respond with json-formatted data consisting of attribute–value pairs.

CircuitPython_Requests can convert a JSON-formatted response from a server into a CPython `dict` object.

We can also fetch and parse json data. We’ll send a HTTP get to a url we know returns a json-formatted response (instead of text data).

Then, the code calls `response.json()` to convert the response to a CPython `dict`.

```python
print("Fetching JSON data from %s"%JSON_GET_URL)
response = requests.get(JSON_GET_URL)
print('.'*40)
print("JSON Response: ", response.json())
print('.'*40)
response.close()
```

**HTTP POST with Requests**

Requests can also POST data to a server by calling the `requests.post` method, passing it a `data` value.
data = '31F'
print("POSTing data to \{0\}: \{1\}".format(JSON_POST_URL, data))
response = requests.post(JSON_POST_URL, data=data)
print('-'*40)

json_resp = response.json()
# Parse out the 'data' key from json_resp dict.
print("Data received from server:", json_resp['data'])
print('-'*40)
response.close()

You can also post json-formatted data to a server by passing json data into the requests.post method.

json_data = {"Date" : "July 25, 2019"}
print("POSTing data to \{0\}: \{1\}".format(JSON_POST_URL, json_data))
response = requests.post(JSON_POST_URL, json=json_data)
print('-'*40)

json_resp = response.json()
# Parse out the 'json' key from json_resp dict.
print("JSON Data received from server:", json_resp['json'])
print('-'*40)
response.close()

Advanced Requests Usage

Want to send custom HTTP headers, parse the response as raw bytes, or handle a response's http status code in your CircuitPython code?

We've written an example to show advanced usage of the requests module below.

```python
# SPDX-FileCopyrightText: 2021 ladyada for Adafruit Industries
# SPDX-License-Identifier: MIT

import board
import busio
from digitalio import DigitalInOut
import adafruit_esp32spi.adafruit_esp32spi_socket as socket
from adafruit_esp32spi import adafruit_esp32spi
import adafruit_requests as requests

# Add a secrets.py to your filesystem that has a dictionary called secrets with
# "ssid" and
# "password" keys with your WiFi credentials. DO NOT share that file or commit it
# into Git or other
# source control.
# pylint: disable=no-name-in-module,wrong-import-order
try:
    from secrets import secrets
except ImportError:
    print("WiFi secrets are kept in secrets.py, please add them there!")
    raise

# If you are using a board with pre-defined ESP32 Pins:
esp32_cs = DigitalInOut(board.ESP_CS)
esp32_ready = DigitalInOut(board.ESP_BUSY)
```

©Adafruit Industries
```python
esp32_reset = DigitalInOut(board.ESP_RESET)

# If you have an externally connected ESP32:
# esp32_cs = DigitalInOut(board.D9)
# esp32_ready = DigitalInOut(board.D10)
# esp32_reset = DigitalInOut(board.D5)

spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
esp = adafruit_esp32spi.ESP_SPIcontrol(spi, esp32_cs, esp32_ready, esp32_reset)

print("Connecting to AP...")
while not esp.is_connected:
    try:
        esp.connect_AP(secrets["ssid"], secrets["password"])
    except RuntimeError as e:
        print("could not connect to AP, retrying: ", e)
        continue

print("Connected to", str(esp.ssid, "utf-8"), "\RSSI:", esp.rssi)

# Initialize a requests object with a socket and esp32spi interface
socket.set_interface(esp)
requests.set_socket(socket, esp)

JSON_GET_URL = "http://httpbin.org/get"

# Define a custom header as a dict.
headers = {"user-agent": "blinka/1.0.0"}

print("Fetching JSON data from %s..." % JSON_GET_URL)
response = requests.get(JSON_GET_URL, headers=headers)
print("-" * 60)

json_data = response.json()
headers = json_data["headers"]
print("Response's Custom User-Agent Header: {0}".format(headers["User-Agent"])))
print("-" * 60)

# Read Response's HTTP status code
print("Response HTTP Status Code: ", response.status_code)
print("-" * 60)

# Close, delete and collect the response data
response.close()
```

WiFi Manager

That simplest example works but it's a little finicky - you need to constantly check WiFi status and have many loops to manage connections and disconnections. For more advanced uses, we recommend using the WiFiManager object. It will wrap the connection/status/requests loop for you - reconnecting if WiFi drops, resetting the ESP32 if it gets into a bad state, etc.

Here's a more advanced example that shows the WiFi manager and also how to POST data with some extra headers:

```python
import time
```
import board
import busio
from digitalio import DigitalInOut
import neopixel
from adafruit_esp32spi import adafruit_esp32spi
from adafruit_esp32spi import adafruit_esp32spi_wifimanager
print("ESP32 SPI webclient test")
# Get wifi details and more from a secrets.py file
try:
    from secrets import secrets
except ImportError:
    print("WiFi secrets are kept in secrets.py, please add them there!")
    raise
# If you are using a board with pre-defined ESP32 Pins:
esp32_cs = DigitalInOut(board.ESP_CS)
esp32_ready = DigitalInOut(board.ESP_BUSY)
esp32_reset = DigitalInOut(board.ESP_RESET)

# If you have an externally connected ESP32:
# esp32_cs = DigitalInOut(board.D9)
# esp32_ready = DigitalInOut(board.D10)
# esp32_reset = DigitalInOut(board.D5)

spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
esp = adafruit_esp32spi.ESP_SPIcontrol(spi, esp32_cs, esp32_ready, esp32_reset)

# Use below for Most Boards
status_light = neopixel.NeoPixel(board.NEOPIXEL, 1, brightness=0.2)
# Uncomment for Most Boards

# Uncomment below for ItsyBitsy M4
# status_light = dotstar.DotStar(board.APA102_SCK, board.APA102_MOSI, 1, brightness=0.2)
# Uncomment below for an externally defined RGB LED
# import adafruit_rgbled
# from adafruit_esp32spi import PWMOut
# RED_LED = PWMOut.PWMOut(esp, 26)
# GREEN_LED = PWMOut.PWMOut(esp, 27)
# BLUE_LED = PWMOut.PWMOut(esp, 25)
# status_light = adafruit_rgbled.RGBLED(RED_LED, BLUE_LED, GREEN_LED)

wifi = adafruit_esp32spi_wifimanager.ESPSPI_WiFiManager(esp, secrets, status_light)

counter = 0

while True:
    try:
        print("Posting data...", end="")
        data = counter
        feed = "test"
        payload = {"value": data}
        response = wifi.post("https://io.adafruit.com/api/v2/"
                           + secrets["aio_username"]
                           + "/feeds/
                           + feed
                           + "/data",
                           json=payload,
                           headers={"X-AIO-KEY": secrets["aio_key"]},
                      )
        print(response.json())
        response.close()
        counter = counter + 1
        print("OK")
    except (ValueError, RuntimeError) as e:
        print("Failed to get data, retrying\n", e)
        wifi.reset()
        continue
response = None
time.sleep(15)

Next, set up an Adafruit IO feed named **test**

- If you do not know how to set up a feed, [follow this page and come back when you've set up a feed named **test**](https://adafruit.io/f5k).

You'll note here we use a secrets.py file to manage our SSID info. The wifimanager is given the ESP32 object, secrets and a neopixel for status indication.

Note, you'll need to add a some additional information to your secrets file so that the code can query the Adafruit IO API:

- **aio_username**
- **aio_key**

You can go to your adafruit.io View AIO Key link to get those two values and add them to the secrets file, which will now look something like this:

```python
# This file is where you keep secret settings, passwords, and tokens!
# If you put them in the code you risk committing that info or sharing it

secrets = {
    'ssid': '_your_ssid_',
    'password': '_your_wifi_password_',
    'timezone': "America/Los_Angeles", # http://worldtimeapi.org/timezones
    'aio_username': '_your_aio_username_',
    'aio_key': '_your_aio_key_'
}
```
We can then have a simple loop for posting data to Adafruit IO without having to deal with connecting or initializing the hardware!

Take a look at your test feed on Adafruit.io and you'll see the value increase each time the CircuitPython board posts data to it!

---

**CircuitPython BLE**

**CircuitPython BLE UART Example**

It's easy to use Adafruit AirLift ESP32 co-processor boards for Bluetooth Low Energy (BLE) with CircuitPython. When you reset the ESP32, you can put it in WiFi mode (the default), or in BLE mode; you cannot use both modes simultaneously.

Here's a simple example of using BLE to connect CircuitPython with the Bluefruit Connect app. Use CircuitPython 6.0.0 or later.

Note: Don’t confuse the ESP32 with the ESP32-S2, which is a different module with a similar name. The ESP32-S2 does not support BLE.

Currently the AirLift support for CircuitPython only provides BLE peripheral support. BLE central is under development. So you cannot connect to BLE devices like Heart Rate monitors, etc., but you can act as a BLE peripheral yourself.
Adafruit AirLift ESP32 FeatherWing Wiring

If you have an Adafruit Airlift ESP32 FeatherWing, you will need to solder three jumpers closed on the bottom side of the board to enable BLE. The rest of the ESP32 pins you need are already jumpered to certain Feather pins.

Update the AirLift Firmware

You will need to update the AirLift's firmware to at least version 1.7.1. Previous versions of the AirLift firmware do not support BLE.

Follow the instructions in the guide below, and come back to this page when you've upgraded the AirLift's firmware:

Upgrade External AirLift Firmware
https://adafru.it/RdC

Ensure the AirLift firmware is version 1.7.1 or higher for BLE to work.

Install CircuitPython Libraries

Make sure you are running the latest version of Adafruit CircuitPython (https://adafru.it/Amd) for your board; you'll need 6.0.0 or later.

Next you'll need to install the necessary libraries to use the hardware and BLE. Carefully follow the steps to find and install these libraries from Adafruit's CircuitPython library bundle (https://adafru.it/uap). Our CircuitPython starter guide has a great page on how to use the library bundle (https://adafru.it/ABU).

Install these libraries from the bundle:

- adafruit_airlift
- adafruit_ble

Before continuing make sure your board's lib folder or root filesystem has the adafruit_airlift and adafruit_ble folders copied over.
Install the Adafruit Bluefruit LE Connect App

The Adafruit Bluefruit LE Connect iOS and Android apps allow you to connect to BLE peripherals that provide a over-the-air "UART" service. Follow the instructions in the Bluefruit LE Connect Guide (https://adafruit.it/Eg5) to download and install the app on your phone or tablet.

Copy and Adjust the Example Program

Copy the program below to the file code.py on CIRCUITPY on your board.

TAKE NOTE: Adjust the program as needed to suit the AirLift board you have. Comment and uncomment lines 12-39 below as necessary.

```python
import board
from adafruit_ble import BLERadio
from adafruit_ble.advertising.standard import ProvideServicesAdvertisement
from adafruit_ble.services.nordic import UARTService
from adafruit_airlift.esp32 import ESP32

# If you are using a Metro M4 Airlift Lite, PyPortal, or MatrixPortal, you can use the default pin settings.
# Leave this DEFAULT line uncommented.
esp32 = ESP32()  # DEFAULT

# If you are using CircuitPython 6.0.0 or earlier, # on PyPortal and PyPortal Titano only, use the pin settings # below. Comment out the DEFAULT line above and uncomment # the line below. For CircuitPython 6.1.0, the pin names # have changed for these boards, and the DEFAULT line # above is correct.
# esp32 = ESP32(tx=board.TX, rx=board.RX)

# If you are using an AirLift FeatherWing or AirLift Bitsy Add-On, # use the pin settings below. Comment out the DEFAULT line above # and uncomment the lines below.
# If you are using an AirLift Breakout, check that these # choices match the wiring to your microcontroller board, # or change them as appropriate.
# esp32 = ESP32(
#     reset=board.D12,
#     gpio0=board.D10,
#     busy=board.D11,
#     chip_select=board.D13,
#     tx=board.TX,
#     rx=board.RX,
# )

# If you are using an AirLift Shield, # use the pin settings below. Comment out the DEFAULT line above # and uncomment the lines below.
# esp32 = ESP32(
#     reset=board.D5,
#     gpio0=board.D6,
```
Talk to the AirLift via the Bluefruit LE Connect App

Start the Bluefruit LE Connect App on your phone or tablet. You should see a CIRCUITPY device available to connect to. Tap the Connect button (1):
You'll then see a list of Bluefruit Connect functions ("modules"). Choose the UART module (2):
On the UART module page, you can type a string and press Send (3). You'll see that string entered, and then see it echoed back (echoing is in gray).
Arduino WiFi

You can use the AirLift with Arduino. Unlike CircuitPython, it work with just about any Arduino chip, even a classic Arduino UNO. However, if you want to use libraries like ArduinoJSON or add sensors and SD card, you'll really want an ATSAMD21 (Cortex M0) or ATSAMD51 (Cortex M4), both of which have plenty or RAM.

First, [make sure you've assembled your AirLift FeatherWing](https://adafru.it/VFX).

Arduino Microcontroller Pin Definitions

Because each Feather uses a different processor, you'll need to include the following pin definitions to your code depending on which board you are using:
Feather M0, M4, 32u4, or NRF52840

```c
#define SPIWIFI       SPI  // The SPI port
#define SPIWIFI_SS    13   // Chip select pin
#define ESP32_RESETN  12   // Reset pin
#define SPIWIFI_ACK   11   // a.k.a BUSY or READY pin
#define ESP32_GPIO0   -1
```

Feather 328P

```c
#define SPIWIFI       SPI  // The SPI port
#define SPIWIFI_SS     4    // Chip select pin
#define ESP32_RESETN   3    // Reset pin
#define SPIWIFI_ACK    2    // a.k.a BUSY or READY pin
#define ESP32_GPIO0   -1
```

Feather NRF52832

```c
#define SPIWIFI       SPI  // The SPI port
#define SPIWIFI_SS     16   // Chip select pin
#define ESP32_RESETN   15   // Reset pin
#define SPIWIFI_ACK    7    // a.k.a BUSY or READY pin
#define ESP32_GPIO0   -1
```

Teensy

```c
#define SPIWIFI       SPI  // The SPI port
#define SPIWIFI_SS     5    // Chip select pin
#define ESP32_RESETN   6    // Reset pin
#define SPIWIFI_ACK    9    // a.k.a BUSY or READY pin
#define ESP32_GPIO0   -1
```

Note: These pin definitions leave the ESP32's GPIO0 pin undefined (-1). If you wish to use this pin - solder the pad on the bottom of the FeatherWing and set `#define ESP32_GPIO0` to the correct pin for your microcontroller.
Note: These pin definitions leave the the ESP32’s GPIO0 pin undefined (-1).

If you wish to use this pin - solder the pad on the bottom of the FeatherWing and set **#define ESP32_GPIO0** to the correct pin for your microcontroller.

Library Install

We're using a variant of the Arduino WiFiNINA library, which is amazing and written by the Arduino team! The official WiFi101 library won't work because it doesn't support the ability to change the pins.

So! We made a fork that you can install.

Click here to download the library:

Download Adafruit's version of WiFiNINA

https://adafruit.it/Evm

Within the Arduino IDE, select Install library from ZIP...
And select the zip you just downloaded.

**First Test**

OK now you have it wired and library installed, time to test it out!

Let's start by scanning the local networks. Load up the `ScanNetworks` example.

At the top you'll see a section where the GPIO pins are defined.
If you don't see this, you may have the wrong WiFiNINA library installed. Uninstall it and re-install the Adafruit one as above.

Compile and upload to your board wired up to the AirLift

```
WiFi Scanning test
MAC: C4:4F:33:0E:B0:BD
Scanning available networks...
** Scan Networks **
number of available networks:10
0) Adafruit      Signal: -56 dBm Encryption: WPA2
1) Consulate Guest  Signal: -59 dBm Encryption: WPA2
2) consulatewireless  Signal: -60 dBm Encryption: WPA2
3) Adafruit      Signal: -66 dBm Encryption: WPA2
4) consulatewireless  Signal: -67 dBm Encryption: WPA2
5) Consulate Guest  Signal: -69 dBm Encryption: WPA2
6) Adafruit      Signal: -69 dBm Encryption: WPA2
7) Consulate Guest  Signal: -71 dBm Encryption: WPA2
8) consulatewireless  Signal: -72 dBm Encryption: WPA2
9) ESP_88EFE6C  Signal: -75 dBm Encryption: None
```

If you don't even get the MAC address printed out, check your wiring.

If you get the MAC address but cannot scan any networks, check your power supply. You need a solid 3-5VDC into Vin in order for the ESP32 not to brown out.

**WiFi Connection Test**

Now that you have your wiring checked, time to connect to the Internet!

Open up the WiFiWebClient example
Open up the secondary tab, arduino_secrets.h. This is where you will store private data like the SSID/password to your network.

You must change these string values before updating to your board!

After you've set it correctly, upload and check the serial monitor. You should see the following. If not, go back, check wiring, power and your SSID/password.
Secure Connection Example

Many servers today do not allow non-SSL connectivity. Lucky for you the ESP32 has a great TLS/SSL stack so you can have that all taken care of for you. Here's an example of a secure WiFi connection:
Note we use `WiFiSSLClient client;` instead of `WiFiClient client;` to require an SSL connection!
Attempting to connect to SSID: Adafruit
Connected to wifi
SSID: Adafruit
IP Address: 10.0.1.179
signal strength (RSSI): -52 dBm

Starting connection to server...
connected to server
HTTP/1.1 200 OK
cache-control: must-revalidate, max-age=600
content-disposition: attachment; filename=json.json
content-type: application/json; charset=utf-8
expires: Wed, 10 Apr 2019 21:17:24 GMT
last-modified: Wed, 10 Apr 2019 21:07:24 GMT
strict-transport-security: max-age=31536000
timing-Allow-Origin: *
x-connection-hash: ab527136393fa0f3bb7779f53c657fae
x-content-type-options: nosniff
x-frame-options: SAMEORIGIN
x-response-time: 12
x-xss-protection: 1; mode=block; report=https://twitter.com/i/xss_report
Content-Length: 197
Accept-Ranges: bytes
Date: Wed, 10 Apr 2019 21:07:24 GMT
Via: 1.1 varnish
Age: 0
Connection: close
X-Served-By: cache-bwi5023-BWI
X-Cache: MISS
X-Timer: S1554930445.534696,VS0,VE25
Vary: Accept-Encoding

["following":false,"id":"20731304","screen_name":"adafruit","name":"Adafruit Industries"
disconnecting from server.
Read 959 bytes
JSON Parsing Demo

This example is a little more advanced - many sites will have API's that give you JSON data. We'll use ArduinoJSON (https://adafru.it/Evn) to convert that to a format we can use and then display that data on the serial port (which can then be re-directed to a display of some sort).

First up, use the Library manager to install ArduinoJSON (https://adafru.it/Evo).

Then load the example JSONdemo

By default it will connect to the Twitter banner image API, parse the username and followers and display them.

```
Attempting to connect to SSID: Adafruit
Connected to wifi
SSID: Adafruit
IP Address: 10.0.1.179
signal strength (RSSI): -51 dBm
Starting connection to server... connected to server
Response:
Twitter username: adafruit
Twitter followers: 159265
```
Adapting Other Examples

Once you’ve got it connecting to the Internet you can check out the other examples.

Upgrade External ESP32 Airlift Firmware

To support BLE on the ESP32 Airlift, you’ll need NINA_W102-1.7.1.bin or later.

External AirLift FeatherWing, Shield, or ItsyWing

External AirLift boards have three optional ESP32 control pins which are not connected by default:

- ESPGIO0
- ESPRX
- ESPTX
Make sure to solder each of these pads together. You will not be able to upload firmware to your ESP32 if they are not connected.

Upload Serial Passthrough code for Feather or ItsyBitsy

First, back up any code and files you have on your CIRCUITPY drive. It will be overwritten by the code you're going to upload to your board. You should not end up losing any files on the QSPI flash, but it's a good idea to back them up anyways.

This section is only for an AirLift FeatherWing with a Feather M4, or an AirLift BitsyWing with an ItsyBitsy M4. If you are using a different hardware combination - scroll down to the “External AirLift Breakout” section.
Download the UF2 for your board to your Desktop.

Feather M0/M4 Passthrough UF2
https://adafruit.it/OYF

Feather NRF52840 Passsthrough UF2
https://adafruit.it/PTE

Itsybitsy Passthrough UF2
https://adafruit.it/IEK

Find the reset button on your board. It's a small, black button, and on most of the boards, it will be the only button available.

Tap this button twice to enter the bootloader. If it doesn't work on the first try, don't be discouraged. The rhythm of the taps needs to be correct and sometimes it takes a few tries.

Once successful, the RGB LED on the board will flash red and then stay green. A new drive will show up on your computer. The drive will be called `boardnameBOOT` where `boardname` is a reference to your specific board. For example, a Feather will have `FEATHERBOOT` and a Trinket will have `TRINKETBOOT` etc. Going forward we'll just call the boot drive `BOOT`
The board is now in bootloader mode. Now find the UF2 file you downloaded. Drag that file to the **BOOT** drive on your computer in your operating system file manager/finder.

The lights should flash again, **BOOT** will disappear. Your board should re-enumerate USB and appear as a COM or Serial port on your computer. Make a note of the serial port by checking the Device Manager (Windows) or typing `ls /dev/cu*` or `/dev/tty*` (Mac or Linux) in a terminal.

If your board is listed in the terminal, proceed to the Uploading nina-fw with esptool section of this guide.

External AirLift Breakout

You'll be turning your Arduino board into a USB to Serial converter. To do this, you'll need a special Arduino sketch named SerialESPPassthrough.ino and an Arduino-compatible board with Native USB support such as the Adafruit Metro M4.

You will also need to make the following connections between the board and the AirLift Breakout:

- Board Pin 12 to ESP32_ResetN
- Board Pin 10 to ESP32_GPIO0
- Board TX to RXI
- Board RX to TX0

Click Download: Project ZIP to download the code below.
```c
#include <Adafruit_NeoPixel.h>

unsigned long baud = 115200;

#if defined(ADAFRUIT_FEATHER_M4_EXPRESS) ||
 defined(ADAFRUIT_FEATHER_M0_EXPRESS) ||
 defined(ARDUINO_AVR_FEATHER32U4) ||
 defined(ARDUINO_NRF52840_FEATHER) ||
 defined(ADAFRUIT_ITSYBITSY_M0) ||
 defined(ADAFRUIT_ITSYBITSY_M4_EXPRESS) ||
 defined(ARDUINO_AVR_ITSYBITSY32U4_3V) ||
 defined(ARDUINO_NRF52_ITSYBITSY)
 // Configure the pins used for the ESP32 connection
#define SerialESP32 Serial1
#define SPIWIFI SPI // The SPI port
#define SPIWIFI_SS 13 // Chip select pin
#define ESP32_RESETN 12 // Reset pin
#define SPIWIFI_ACK 11 // a.k.a BUSY or READY pin
#define ESP32_GPIO0 10
#define NEOPIXEL_PIN 8
#elif defined(ARDUINO_AVR_FEATHER328P)
#define SerialESP32 Serial1
#define SPIWIFI SPI // The SPI port
#define SPIWIFI_SS 4 // Chip select pin
#define ESP32_RESETN 3 // Reset pin
#define SPIWIFI_ACK 2 // a.k.a BUSY or READY pin
#define ESP32_GPIO0 -1
#define NEOPIXEL_PIN 8
#elif defined(TEENSYDUINO)
#define SerialESP32 Serial1
#define SPIWIFI SPI // The SPI port
#define SPIWIFI_SS 5 // Chip select pin
#define ESP32_RESETN 6 // Reset pin
#define SPIWIFI_ACK 9 // a.k.a BUSY or READY pin
#define ESP32_GPIO0 -1
#define NEOPIXEL_PIN 8
#elif defined(ARDUINO_NRF52832_FEATHER)
#define SerialESP32 Serial1
#define SPIWIFI SPI // The SPI port
#define SPIWIFI_SS 16 // Chip select pin
#define ESP32_RESETN 15 // Reset pin
#define SPIWIFI_ACK 7 // a.k.a BUSY or READY pin
#define ESP32_GPIO0 -1
```

---

© Adafruit Industries
```c
#define NEOPIXEL_PIN   8
#elif !defined(SPIWIFI_SS)  // if the wifi definition isn't in the board variant
// Don't change the names of these #define's! they match the variant ones
#define SerialESP32   Serial1
#define SPIWIFI       SPI
#define SPIWIFI_SS    10   // Chip select pin
#define SPIWIFI_ACK    7   // a.k.a BUSY or READY pin
#define ESP32_RESETN   5   // Reset pin
#define ESP32_GPIO0   -1   // Not connected
#define NEOPIXEL_PIN   8
#endif
#if defined(ADAFRUIT_PYPORTAL)
#define PIN_NEOPIXEL   2
#elif defined(ADAFRUIT_METRO_M4_AIRLIFT_LITE)
#define PIN_NEOPIXEL   40
#endif
Adafruit_NeoPixel pixel = Adafruit_NeoPixel(1, PIN_NEOPIXEL, NEO_GRB + NEO_KHZ800);

void setup() {
  Serial.begin(baud);
  pixel.begin();
  pixel.setPixelColor(0, 10, 10, 10); pixel.show();
  while (!Serial);
  pixel.setPixelColor(0, 50, 50, 50); pixel.show();
  delay(100);
  SerialESP32.begin(baud);
  pinMode(SPIWIFI_SS, OUTPUT);
  pinMode(ESP32_GPIO0, OUTPUT);
  pinMode(ESP32_RESETN, OUTPUT);
  // manually put the ESP32 in upload mode
  digitalWrite(ESP32_GPIO0, LOW);
  digitalWrite(ESP32_RESETN, LOW);
  delay(100);
  digitalWrite(ESP32_RESETN, HIGH);
  pixel.setPixelColor(0, 20, 20, 0); pixel.show();
  delay(100);
}

void loop() {
  while (Serial.available()) {
    pixel.setPixelColor(0, 10, 0, 0); pixel.show();
    SerialESP32.write(Serial.read());
  }
  while (SerialESP32.available()) {
    pixel.setPixelColor(0, 0, 0, 10); pixel.show();
    Serial.write(SerialESP32.read());
  }
}
```

**Code Usage**

Unzip the file, and open the SerialESPPasssthrough.ino file in the Arduino IDE.
If you’re using the AirLift FeatherWing, AirLift Shield or AirLift Bitsy Add-On, use the PassThrough UF2 instructions above.

If you have an AirLift Breakout (or are manually wiring up any of the boards above), change the following pin definitions in the sketch to match your wiring:

```cpp
#elif !defined(SPIWIFI_SS)  // if the wifi definition isn't in the board variant
    // Don't change the names of these #define's! they match the variant ones
#define SerialESP32   Serial1
#define SPIWIFI       SPI
#define SPIWIFI_SS    10   // Chip select pin
#define SPIWIFI_ACK    7   // a.k.a BUSY or READY pin
#define ESP32_RESETN   5   // Reset pin
#define ESP32_GPIO0   -1   // Not connected
#define NEOPIXEL_PIN   8
#endif
```

Using the Arduino IDE, upload the code to your board (Sketch->Upload).

After uploading, the board should enumerate USB and appear as a COM or Serial port on your computer.

Make a note of the serial port by checking the Device Manager (Windows) or typing in `ls /dev/cu*` or `/dev/tty*` (Mac or Linux) in a terminal.

```
$ ls /dev/cu.*
/dev/cu.Bluetooth-Incoming-Port /dev/cu.usbmodem1432201
```

This guide assumes you have Python3 installed. If you have not installed it, navigate to the Python downloads page (https://www.python.org/downloads) and install the latest release.

**Install esptool.py**

Esptool is an application which can communicate with the ROM bootloader (https://adafru.it/LKe) in Espressif chips.

To install esptool, run the following in your terminal:

```
pip3 install esptool
```
Burning nina-fw with esptool

Click the link below to download the latest nina-fw .bin file. Unzip it and save the .bin file to your desktop.

Latest nina-fw .bin file
https://adafru.it/G3D

If you're using macOS or Linux - run the following command, replacing /dev/ttyACM0 with the serial port of your board and NINA_W102-1.6.0 with the binary file you're flashing to the ESP32.

    esptool.py --port /dev/ttyACM0 --before no_reset --baud 115200 write_flash 0 NINA_W102-1.6.0.bin

If you're using Windows - run the following command, replacing COM7 with the serial port of your board and NINA_W102-1.6.0 with the binary file you're flashing to the ESP32.

    esptool.py --port COM7 --before no_reset --baud 115200 write_flash 0 NINA_W102-1.6.0.bin

The command should detect the ESP32 and will take a minute or two to upload the firmware.

If ESPTool doesn't detect the ESP32, make sure you've uploaded the correct .UF2 file to the bootloader and are using the correct serial port.
Once the firmware is fully uploaded, the ESP32 will reset.

Verifying the Upgraded Firmware Version

To verify everything is working correctly, we'll load up either an Arduino sketch or CircuitPython code. At this point, you must desolder the connections between the Optional ESP32 control pins you made earlier using a solder sucker (https://adafru.it/FWk) or a bit of solder wick (https://adafru.it/yrC).

Arduino

If you were previously using your ESP32 with Arduino, you should load up an Arduino sketch to verify everything is working properly and the version of the nina-fw correlates with the version the sketch reads.

Open up File->Examples->WiFiNINA->ScanNetworks and upload the sketch. Then, open the Serial Monitor. You should see the firmware version printed out to the serial monitor.

```
/dev/cu.usbmodem1412301 (Adafruit PyPortal M4 (SAMD51))

Scanning available networks...
** Scan Networks **
number of available networks:10
  0) DreamingDoig Signal: -58 dBm Encryption: WPA2
  1) MySpectrumWiFi.co.uk-2G Signal: -66 dBm Encryption: WPA2
  2) Raising_1SIX7 Signal: -74 dBm Encryption: WPA2
  3) TG1672G2 Signal: -74 dBm Encryption: WPA2
  4) MySpectrumWiFi1f5-2G Signal: -77 dBm Encryption: WPA2
  5) MySpectrumWiFi6a-2G Signal: -77 dBm Encryption: WPA2

New Firmware Version
```
CircuitPython

If you were previously using your ESP32 project with CircuitPython, you'll need to first reinstall CircuitPython firmware (UF2) for your board. The QSPI flash should have retained its contents. If you don't see anything on the CIRCUITPY volume, copy files from the backup you made earlier to CIRCUITPY.

To verify the new ESP32 WiFi firmware version is correct, follow the Connect to WiFi step in this guide (https://adafru.it/Eao) and come back here when you've successfully ran the code. The REPL output should display the firmware version you flashed.

code.py output:
ESP32 SPI webclient test
ESP32 found and in idle mode
Firmware vers. bytearray(b'1.3.0\x00')
MAC addr: ['0x19', '0x5c', '0xd', '0x33', '0x4f', '0xc4']

Downloads

Files

- ESP32 WROOM32 Datasheet (https://adafru.it/EVE)
- EagleCAD files on GitHub (https://adafru.it/EVF)
- Fritzing object in Adafruit Fritzing Library (https://adafru.it/EVG)
- 3D Models on GitHub (https://adafru.it/FcS)